

More than Rectangles and Tubes:

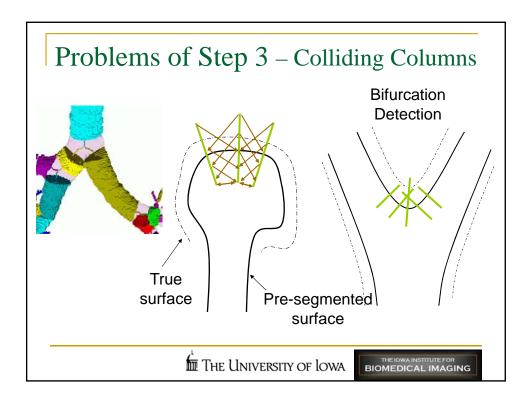
Generalization to complex shapes

- Step 1: Pre-segmentation
 - □ Derive topology of objects of interest from image data → approximate segmentation
- Step 2: Mesh Generation
 - Specify structure of a base graph defining neighboring relations among voxels on the sought surfaces
- Step 3: Image Resampling
 - Resample along a ray intersecting every vertex of the mesh forming graph columns.
- Step 4: Graph Construction
 - Weighted directed graph G built using from columns, with neighboring relations, smoothness constraints, and inter-surface separation.
- Step 5: Graph Search
 - Searching for optimal closed set.

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Electric Lines of Force (ELF)

• An electric field theory motivated search direction

$$E_i = \frac{1}{4\pi\varepsilon_0} \frac{Q}{r^2} \hat{r}$$

$$E = \sum_{i} E_{i}$$

- Non-intersecting
- □ Easy to compute
- □ Expanding to any positions

Point charges

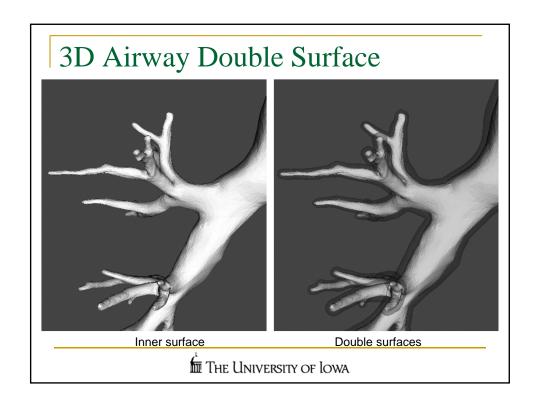
Iso-electric field

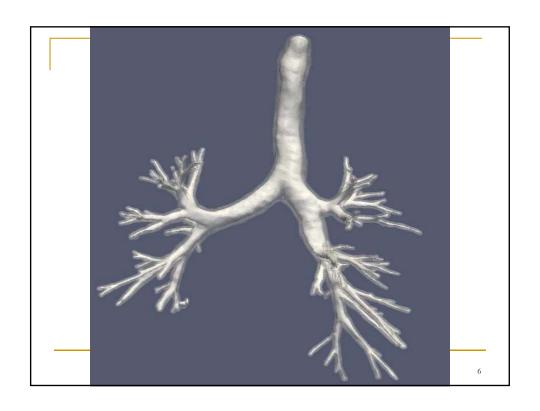
Electric lines of force (ELF)

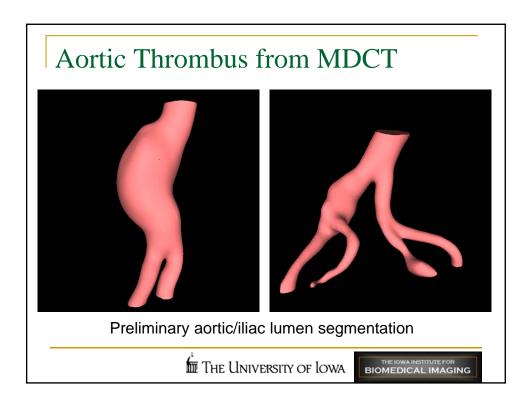
Non-ELF medial-surface approach also possible

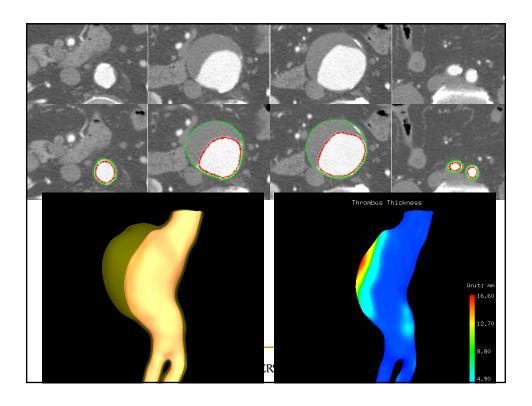
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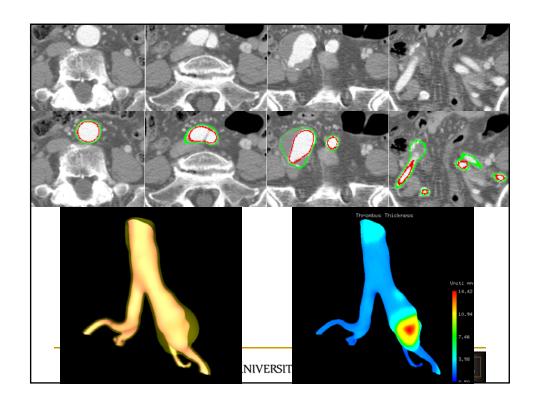
4

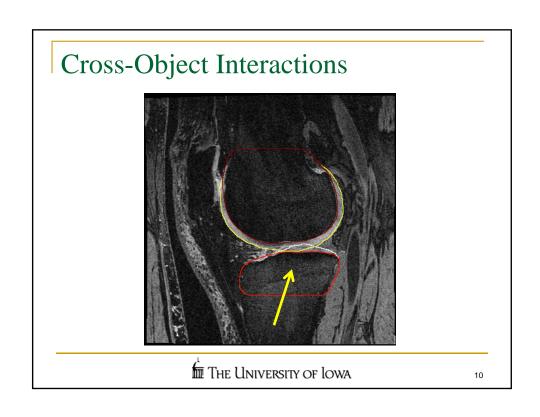












Multi-object 3D segmentation

- Regions of object-to-object interactions
 - □ reflected in inter-graph arcs
- Steps:
 - □ Identify regions of pairwise interaction
 - □ Link interacting surfaces = create inter-graph arcs
 - □ Build/solve resulting graph
- Example
 - □ Prostate Bladder (Rectum)
 - □ Knee-joint cartilage segmentation
 - Femur/Tibia/Patella cartilage thickness

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