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Selected Problems

- 1. Show that if the motion of a camera is only a translation along the line of sight (by convention the *Z* axis), then the vanishing point known as the focus of expansion (or contraction) is at the center of the imaging plane, in image coordinates.
- 2. Suppose a plane in 3D with relative instantaneous motion $\vec{T} = (1,1,1)^T$ and $\vec{\omega} = (0.1,0.1,0)^T$, with unit normal $\vec{n} = (0,0,1)^T$ and d = 10. Find the other plane (and its motion) that generates the same image motion field, by computing the dual solution.
- 3. What is the normal velocity of an image region for which $\nabla I = (1,1)^T$ and $I_t = 1$? Why cannot we compute full velocity with only the provided data?
- 4. Compute the derivative of the following Gaussian:

$$\frac{1}{\sqrt{2\pi}\sigma}\exp\left\{\frac{-x^2}{2\sigma^2}\right\}$$

5. What would you be computing by creating a kernel with the result of the previous question and performing a convolution on an image area? Justify your answer.