Computing the real solutions of polynomial systems with the RegularChains library in MAPLE

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RealTriangularize

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- Branch cut analysis
- 4 Biochemical network analysis
- 5 Reachibility problem for hybrid systems

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## The RegularChains library in MAPLE

#### Design goals

- Solving polynomial systems over  $\mathbb{Q}$  and  $\mathbb{F}_p$ , including parametric systems and semi-algebraic systems.
- Offering tools to manipulate their solutions.
- Organized around the concept of a **regular chain**, accommodating all types of solving and providing space-and-time efficiency.

#### Features

- Use of types for algebraic structures: polynomial\_ring, regular\_chain, constructible\_set, quantifier\_free\_formula, regular\_semi\_algebraic\_system.
- Top level commands: PolynomialRing, Triangularize, RealTriangularize SamplePoints, ...
- Tool kits: ConstructibleSetTools, ParametricSystemTools, FastArithmeticTools, SemiAlgebraicSetTools, ...

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# Solving for the real solutions of polynomial systems

#### **Classical tools**

- Isolating the real solutions of zero-dimensional polynomial systems: SemiAlgebraicSetTools:-RealRootIsolate
- Real root classification of parametric polynomial systems: ParametricSystemTools:-RealRootClassification
- Cylindrical algebraic decomposition of polynomial systems: SemiAlgebraicSetTools:-CylindricalAlgebraicDecompose

#### New tools

- Triangular decomposition of semi-algebraic systems: RealTriangularize
- Sampling all connected components of a semi-algebraic system: SamplePoints
- Set-theoretical operations on semi-algebraic sets: SemiAlgebraicSetTools:-Difference

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   RealTriangularize

### Regular semi-algebraic system

#### Notation

- Let  $T \subset \mathbb{Q}[x_1 < \ldots < x_n]$  be a regular chain with  $\mathbf{y} := \{ \operatorname{mvar}(t) \mid t \in T \}$  and  $\mathbf{u} := \mathbf{x} \setminus \mathbf{y} = u_1, \ldots, u_d$ .
- Let P be a finite set of polynomials, s.t. every f ∈ P is regular modulo sat(T).
- Let  $\mathcal{Q}$  be a quantifier-free formula of  $\mathbb{Q}[\mathbf{u}]$ .

#### Definition

```
We say that R := [Q, T, P_{>}] is a regular semi-algebraic system if:
```

- (i)  $\mathcal Q$  defines a non-empty open semi-algebra ic set S in  $\mathbb R^d$ ,
- (ii) the regular system [T, P] specializes well at every point u of S
- (iii) at each point u of S, the specialized system  $[T(u), P(u)_{>}]$  has at least one real solution.

 $Z_{\mathbb{R}}(R) = \{(u,y) \mid \mathcal{Q}(u), t(u,y) = 0, p(u,y) > 0, orall(t,p) \in \mathcal{T} imes P\}$ 

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 $Z_{\mathbb{R}}(R) = \{(u,y) \mid \mathcal{Q}(u), t(u,y) = 0, p(u,y) > 0, \forall (t,p) \in T \times P\}.$ 

#### Overview

#### Example

The system  $[Q, T, P_{>}]$ , where

$$\mathcal{Q} := a > 0, \ T := \left\{ egin{array}{c} y^2 - a = 0 \\ x = 0 \end{array} 
ight., \ P_> := \{y > 0\}$$

is a regular semi-algebraic system.



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Overview

# RealTriangularize applied to the *Eve* surface (1/2)



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RealTriangularize

▲ ■ ● ■ • つへで ISSAC 2011 8 / 17 Overview

### RealTriangularize applied to the *Eve* surface (2/2)





### 2 Solver verification

- 3 Branch cut analysis
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### Are these two different output equivalent?



Given a triangle with edge lengths a, b, c(denoting the respective edges a, b, c too) the following two conditions  $S_1, S_2$  are both characterizing the fact that the external bisector of the angle of a, c intersects with bon the other side of a than the triangle:

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 $\begin{array}{l} S_1 = a > 0 \wedge b > 0 \wedge c > 0 \wedge a < b + c \wedge b < a + c \wedge c < a + b \wedge \\ \left( b^2 + a^2 - c^2 \leq 0 \right) \quad \lor \quad \left( c (b^2 + a^2 - c^2)^2 < a b^2 (2ac - (c^2 + a^2 - b^2)) \right), \end{array}$ 

 $S_2 = a > 0 \land b > 0 \land c > 0 \land a < b + c \land b < a + c \land c < a + b \land c - a > 0.$ 



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## Is this simplification correct?

#### The original problem

The branch cut of  $\sqrt{z}$  is conventionally:

$$\{z\in\mathbb{C}\ \mid\ \Re(z)<0\ \land\ \Im(z)=0\}.$$

Do the following equations hold for all  $z \in \mathbb{C}$ :

$$\sqrt{z-1}\sqrt{z+1} = \sqrt{z^2-1}$$
 and  $\sqrt{1-z}\sqrt{1+z} = \sqrt{1-z^2}$ .

#### Turning the question to sampling

- The branch cuts of each formula is a semi-algebraic system S given as the disjunction of 3 others  $S_1$ ,  $S_2$ ,  $S_3$  (one per  $\sqrt{-}$ ).
- Consider CAD-cells  $C_1, \ldots, C_e$ , forming an intersection-free basis refining the connected components of  $S_1$ ,  $S_2$ ,  $S_3$ .
- By virtue of the *Modromy Theorem*, it is sufficient to check whether the formula holds at a sample point of each of  $C_1, \ldots, C_e$ .

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# Is there a unique positive equilibrium?

Allosteric enzym

Cascad of polymerisation

$$E + S \quad \stackrel{k_{1}}{\underset{k_{2}}{\longrightarrow}} C \qquad P_{1} + P_{1} \quad \stackrel{k_{2}}{\underset{k_{2}}{\longrightarrow}} P_{2}$$

$$E + C \quad \stackrel{k_{3}}{\underset{k_{4}}{\longrightarrow}} F \qquad P_{1} + P_{2} \quad \stackrel{k_{3}}{\underset{k_{3}}{\longrightarrow}} P_{3}$$

$$\stackrel{\frac{1}{2}C - \frac{1}{2}E + S - \frac{1}{2}C_{0} + \frac{1}{2}E_{0} - S_{0} = 0 \qquad \vdots$$

$$\stackrel{\frac{1}{2}C + \frac{1}{2}E + F - \frac{1}{2}C_{0} - \frac{1}{2}E_{0} - F_{0} = 0 \qquad \vdots$$

$$k_{1}ES - k_{2}C - k_{3}EC + k_{4}F = 0 \qquad P_{1} + P_{n-1} \quad \stackrel{k_{n}}{\underset{k_{n}}{\longrightarrow}} P_{n}$$

$$E, S, C, F, E_{0}, S_{0}, C_{0}, F_{0}, k_{1}, k_{2}, k_{3}, k_{4} > 0.$$

• Each system is viewed as parametric in the initial concentrations and kinetic velocities.

• We show that, generically, there is a unique positive equilibrium.

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$$\stackrel{\frac{1}{2}C - \frac{1}{2}E + S - \frac{1}{2}C_0 + \frac{1}{2}E_0 - S_0 = 0 \\ \stackrel{\frac{1}{2}C + \frac{1}{2}E + F - \frac{1}{2}C_0 - \frac{1}{2}E_0 - F_0 = 0 \\ \stackrel{k_1ES - k_2C - k_3EC + k_4F = 0 \\ -2k_3EC + 2k_4F = 0 \\ E, S, C, F, E_0, S_0, C_0, F_0, k_1, k_2, k_3, k_4 > 0.$$

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### Which states can be reached from the intial one?

#### Hybrid systems with linear control

- Given  $A \in \mathbb{R}^{n \times n}$ ,  $B \in \mathbb{R}^{n \times m}$  consider  $\dot{\xi} = A\xi + Bu$  where  $\xi(t) \in \mathbb{R}^n$  is the state of the system at time t and  $u : \mathbb{R} \to \mathbb{R}^m$  is a piecewise continuous function which is called the control input.
- With  $x = \xi(0)$  and a control input u, we have:

$$\xi(t) = \Phi(x, u, t) = e^{At}x + \int_0^t e^{A(t-\tau)}Bu(\tau)d\tau.$$

• Question: Given  $x = \xi(0)$ , which values  $\xi(t)$  can the reached?

### The (Lafferriere et al. 2001) example

$$\Phi(x_1, x_2, u, t) = \left(x_1 e^{2t} + \frac{2}{3}u(-e^{2t} + e^{\frac{1}{2}t}), x_2 e^{-t} + \frac{1}{2}u(e^t - e^{-t})\right)$$

Let  $z = e^{\frac{1}{2}t}$ , the problem reduces to compute the  $(y_1, y_2)$  such that:

 $\exists u \exists z (0 \le u \land z \ge 1 \land p_1 = 0 \land p_2 = 0) \text{ where} \\ p_1 = y_1 - \frac{2}{3}u(-z^4 + z) \text{ and } p_2 = y_2z^2 - \frac{1}{2}u(z^4 - 1) \end{aligned}$ 

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