

# Solving Polynomial Systems Symbolically and in Parallel

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## Solving polynomial systems ...

$$\begin{cases} x^2 + y + z = 1 \\ x + y^2 + z = 1 \\ x + y + z^2 = 1 \end{cases}$$

The output with `phc` the *symp.-num.* software of J. Verschelde:

```
solution 1 :      start residual : 3.968E-12      #iterations : 1      success
  x : 9.99999695984909E-01  4.13938269379988E-07
  y : 3.04015091103714E-07 -4.13938269379988E-07
  z : 3.04015090976779E-07 -4.13938269379988E-07
== err : 2.154E-06 = rco : 1.197E-07 = res : 9.920E-13 = complex regular ==
solution 2 :      start residual : 1.388E-16      #iterations : 1      success
  x : 4.14213562373095E-01  2.35098870164458E-38
  y : 4.14213562373095E-01 -1.67507944992176E-37
  z : 4.14213562373095E-01  1.29304378590452E-37
== err : 7.517E-16 = rco : 6.017E-02 = res : 5.551E-17 = real regular ==
solution 3 :      start residual : 2.400E-12      #iterations : 1      success
  x : 1.80048038888678E-08  4.29782537417684E-07
  y : 9.99999981995196E-01 -4.29782537417684E-07
  z : 1.80048038262633E-08  4.29782537417684E-07
== err : 1.344E-06 = rco : 7.463E-08 = res : 5.995E-13 = complex regular ==
```

```

solution 4 :    start residual : 9.614E-13    #iterations : 1    success
  x : 1.00000024904061E+00 -3.93267692590196E-08
  y : -2.49040612161639E-07  3.93267692590197E-08
  z : -2.49040612108234E-07  3.93267692590197E-08
== err : 8.657E-07 = rco : 4.806E-08 = res : 2.400E-13 = complex regular ==
solution 5 :    start residual : 2.745E-12    #iterations : 1    success
  x : 3.58839953269127E-07  1.89357516639334E-07
  y : 3.58839953269127E-07  1.89357516639334E-07
  z : 9.99999641160047E-01 -1.89357516639334E-07
== err : 1.645E-06 = rco : 7.071E-08 = res : 6.863E-13 = complex regular ==
solution 6 :    start residual : 1.744E-34    #iterations : 1    success
  x : -2.41421356237309E+00  0.00000000000000E+00
  y : -2.41421356237309E+00  0.00000000000000E+00
  z : -2.41421356237309E+00 -1.00577224408752E-106
== err : 3.611E-35 = rco : 4.142E-01 = res : 6.868E-106 = real regular ==
solution 7 :    start residual : 1.112E-12    #iterations : 1    success
  x : -2.64786238552867E-07 -4.67724648385200E-08
  y : -2.64786238552867E-07 -4.67724648385200E-08
  z : 1.00000026478624E+00  4.67724648385200E-08
== err : 9.341E-07 = rco : 4.530E-08 = res : 2.779E-13 = complex regular ==
solution 8 :    start residual : 2.045E-12    #iterations : 1    success
  x : 1.42636460554469E-07 -3.16738323586431E-07
  y : 9.99999857363539E-01  3.16738323586431E-07
  z : 1.42636460467758E-07 -3.16738323586431E-07
== err : 1.378E-06 = rco : 7.656E-08 = res : 5.117E-13 = complex regular ==
=====

```

A list of 8 solutions has been refined :

```

Number of regular solutions   : 8.
Number of singular solutions  : 0.
Number of real solutions      : 2.
Number of complex solutions   : 6.
Number of clustered solutions : 0.
Number of failures            : 0.

```

## Solving polynomial systems symbolically ...

$$\left\{ \begin{array}{l} x^2 + y + z = 1 \\ x + y^2 + z = 1 \\ x + y + z^2 = 1 \end{array} \right. \quad \text{has Gröbner basis :}$$

$$\left\{ \begin{array}{l} z^6 - 4z^4 + 4z^3 - z^2 = 0 \\ 2z^2y + z^4 - z^2 = 0 \\ y^2 - y - z^2 + z = 0 \\ x + y + z^2 - 1 = 0 \end{array} \right. \quad \text{and triangular decomposition :}$$

$$\left\{ \begin{array}{l} z = 1 \\ y = 0 \\ x = 0 \end{array} \right. \cup \left\{ \begin{array}{l} z = 0 \\ y = 1 \\ x = 0 \end{array} \right. \cup \left\{ \begin{array}{l} z = 0 \\ y = 0 \\ x = 1 \end{array} \right. \cup \left\{ \begin{array}{l} z^2 + 2z - 1 = 0 \\ y = z \\ x = z \end{array} \right.$$

Processor  $P_0$

$$x^2 + y + z = 1$$

$$x + y^2 + z = 1$$

$$x + y + z^2 = 1$$

$$z = 1$$

$$y = 0$$

$$x = 0$$

Processor  $P_1$

$$z = 0$$

$$y = 1$$

$$x = 0$$

Processor  $P_2$

$$z = 0$$

$$y = 0$$

$$x = 1$$

Processor  $P_3$

$$z^2 + 2z - 1 = 0$$

$$y = z$$

$$x = z$$

Processor  $P_4$

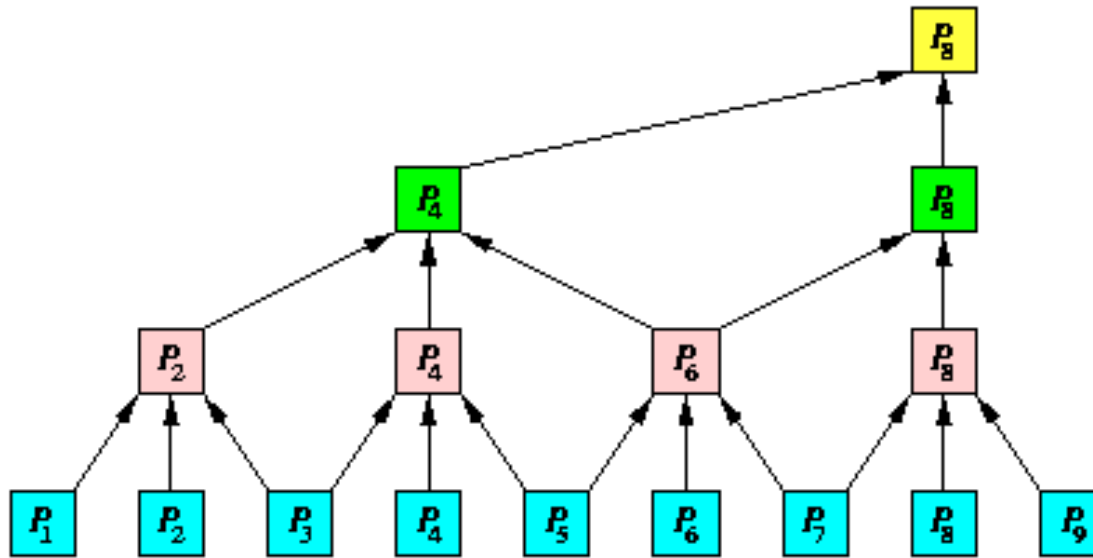
## An example of efficient parallelization

Consider a tridiagonal linear system of order  $n$ :

$$\begin{array}{ccccccc}
 \dots & & \dots & & \dots & & \dots \\
 & a_{i-2}x_{i-2} & + b_{i-1}x_{i-1} & + c_i x_i & & & = e_{i-1} \\
 & & a_{i-1}x_{i-1} & + b_i x_i & + c_{i+1}x_{i+1} & & = e_i \\
 & & & a_i x_i & + b_{i+1}x_{i+1} & + c_{i+2}x_{i+2} & = e_{i+1} \\
 & & & & \dots & \dots & \dots
 \end{array}$$

For every even  $i$  replacing  $x_i$  with  $-\frac{e_i - c_{i+1}x_{i+1} - a_{i-1}x_{i-1}}{b_i}$  leads to another tridiagonal system of order  $n/2$ :

$$\begin{array}{ccccccc}
 \dots & & \dots & & \dots & & \dots \\
 & A_{i-3}x_{i-3} & + B_{i-1}x_{i-1} & + C_{i+1}x_{i+1} & & & = E_{i-1} \\
 & & A_{i-1}x_{i-1} & + B_{i+1}x_{i+1} & + C_{i+3}x_{i+3} & & = E_{i+1} \\
 & & & \dots & \dots & \dots & \dots
 \end{array}$$



Observe that, on this example:

- the number of processors, here  $p = n$ , can be set such that
- the number of parallel steps, here  $O(\log n)$ , is known and small,
- processors activity (scheduling) is easy to organize,
- data-communication is not intensive.

## Why solving non-linear systems is much more difficult?

Let  $F \subset K[X]$  with  $X = x_1 < \cdots < x_n$  and a coefficient field  $K$ . Let  $d$  be the maximum (total) degree of a monomial in  $F$ .

Let  $V(F) \subset \overline{K}^n$  be the zero set of  $F$ , where  $\overline{K}$  is an algebraically closed field containing  $K$ . For instance  $K = \mathbb{Q}$  and  $\overline{K} = \mathbb{C}$ .

- $V(F)$  may consist of components of **different dimension**: points, curves, surfaces,  $\dots$ ,
- Even if  $V(F)$  is finite, it may contain  $O(d^n)$  points,
- The idea of *substitution* or *simplification* is much **more complicated** than in the linear case and leads to the notion of a *Gröbner basis*,
- **Large intermediate data.**



## What is a Gröbner basis?

- Assume  $F$  is a **linear** system. Then, a solution of  $F$  is a **solved** system  $S$  for  $x_1 < \dots < x_n$  which reduces to 0 (i.e. cancels) all polynomials in  $F$ . Moreover, up to trivial transformations, the set  $S$  is unique.
- Now, assume that  $F$  is **not linear**. Then, a Gröbner basis of  $F$  is a system  $B$  which reduces to 0 all polynomials in the ideal generated by  $F$ . Moreover, up to trivial transformations, the set  $B$  is unique.

$$\left\{ \begin{array}{l} x^2 + y + z = 1 \\ x + y^2 + z = 1 \\ x + y + z^2 = 1 \end{array} \right. \quad \underline{\text{has Gröbner basis}} : \quad \left\{ \begin{array}{l} z^6 - 4z^4 + 4z^3 - z^2 = 0 \\ 2z^2y + z^4 - z^2 = 0 \\ y^2 - y - z^2 + z = 0 \\ x + y + z^2 - 1 = 0 \end{array} \right.$$

## Parallelizing the computation of Gröbner bases

**Input:**  $F \subset K[X]$  and an admissible monomial ordering  $\leq$ .

**Output:**  $G$  a reduced Gröbner basis w.r.t.  $\leq$  of the ideal  $\langle F \rangle$  generated by  $F$ .

**repeat**

(S)  $B := \text{MinimalAutoreducedSubset}(F, \leq)$

(R)  $A := \text{S\_Polynomials}(F) \cup F;$

$R := \text{Reduce}(A, B, \leq)$

(U)  $R := R \setminus \{0\}; F := F \cup R$

**until**  $R = \emptyset$

**return**  $B$

(Bündgen, Göbel & W. Küchlin, 1994) (Chakrabarti & Yelick, 1993, 1994)  
(Attardi & Traverso, 1996) (Leykin, 2004)

## To go further: triangular decompositions

- The zero set  $V(F)$  admits a decomposition (unique when minimal)

$$V(F) = V(F_1) \cup \cdots \cup V(F_e),$$

s.t.  $F_1, \dots, F_e \subset K[X]$  and every  $V(F_i)$  **cannot** be decomposed further.

- Moreover, for each  $V(F_i)$  the following holds, up to renumbering the variables. If  $V(F_i)$  has dimension  $d$ , then there exist polynomials  $T_{d+1}, \dots, T_n$  with respective main variables  $x_{d+1}, \dots, x_n$  and respective corresponding leading coefficients  $h_{d+1}, \dots, h_n$  such that

1.  $h_{d+1}, \dots, h_n$  are polynomials in  $K[x_1, \dots, x_d]$ ,
2.  $\sqrt{\langle F_i \rangle} = \langle T_{d+1}, \dots, T_n \rangle : h^\infty$  where  $h = h_{d+1} \cdots h_n$ .

Up to technical details, this means that each  $V(F_i)$  is the zero set of a polynomial system with a **triangular shape**, called a *regular chain*.

Regular chains for the  $V(F_i)$ 's form a *triangular decomposition* of  $V(F)$ .

## The characteristic set method

**Input:**  $F \subset K[X]$  and a variable ordering  $\leq$ .

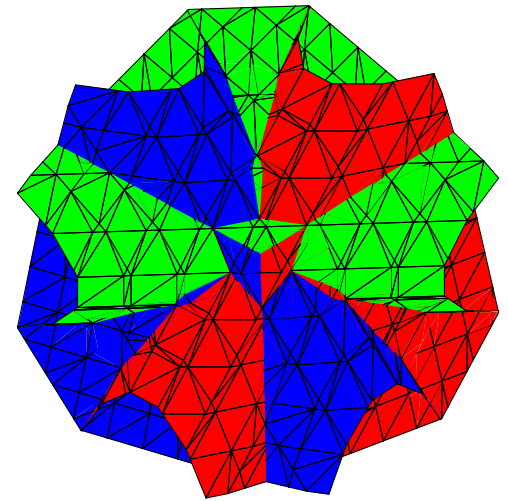
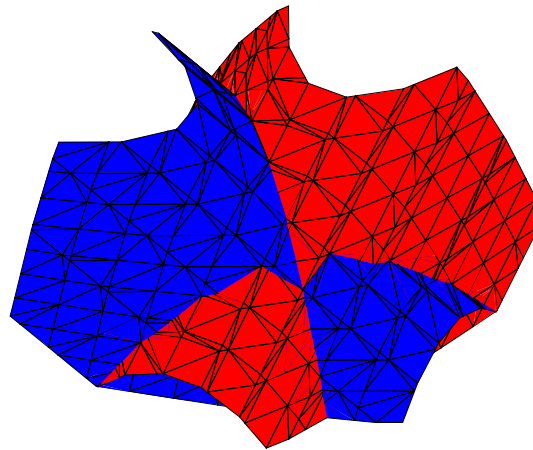
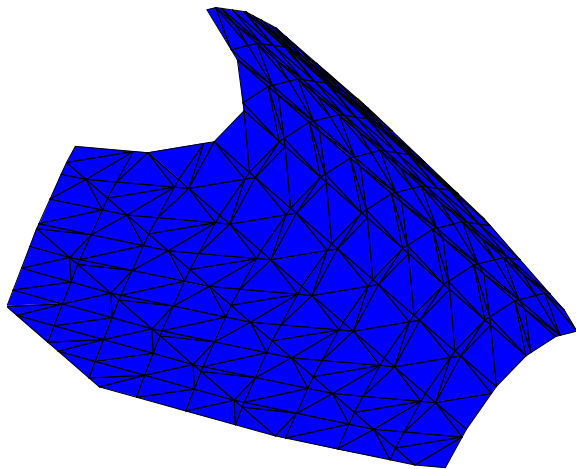
**Output:**  $C$  an autoreduced characteristic set of  $F$  (in the sense of Wu).

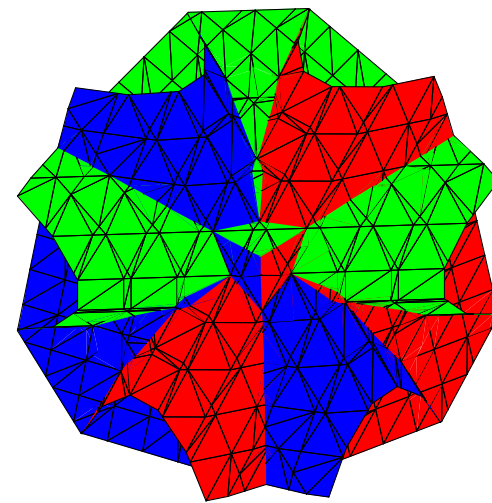
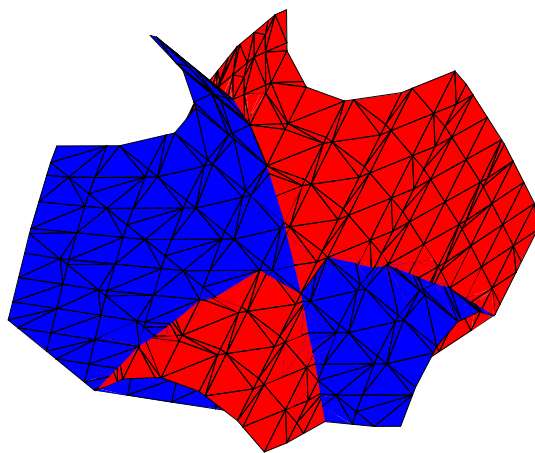
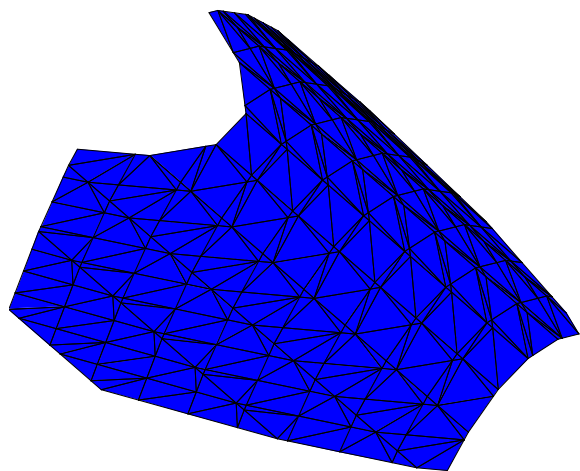
```
repeat
(S)  $B := \text{MinimalAutoreducedSubset}(F, \leq)$ 
(R)  $A := F \setminus B;$ 
       $R := \text{PseudoReduce}(A, B, \leq)$ 
(U)  $R := R \setminus \{0\}; F := F \cup R$ 
until  $R = \emptyset$ 
return  $B$ 
```

- Repeated calls to this procedure computes a decomposition of  $V(F)$ .
- Cannot start computing the 2nd component before the 1st is completed.
- (Ajwa, 1998), (Y.W. Wu, W.D. Liao, D.D. Liu & P.S. Wang, 2003)  
(Y.W. Wu, G.W. Yang, H. Yang, H.M. Zheng & D.D. Liu, 2005)

# Triangular decompositions: a geometrical approach

$$\left\{ \begin{array}{l} x^2 + y + z = 1 \end{array} \right. \left\{ \begin{array}{l} x^2 + y + z = 1 \\ x + y^2 + z = 1 \end{array} \right. \left\{ \begin{array}{l} x^2 + y + z = 1 \\ x + y^2 + z = 1 \\ x + y + z^2 = 1 \end{array} \right.$$

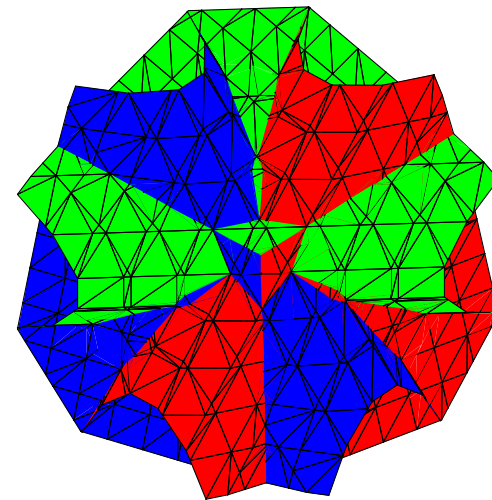
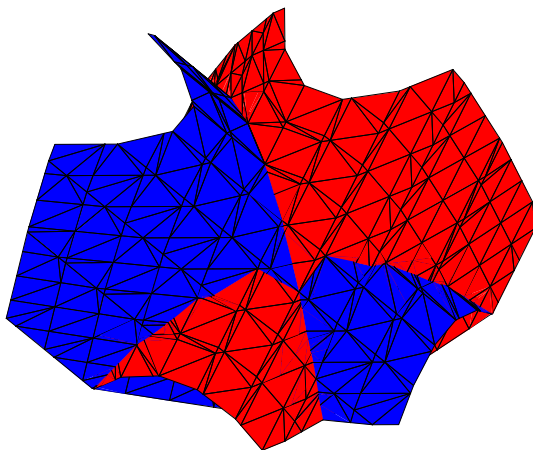
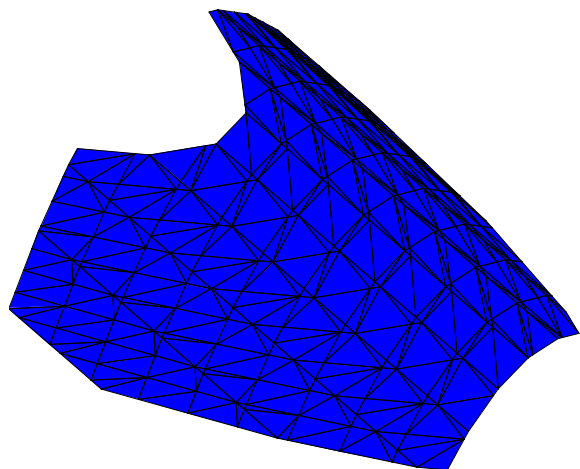




$$\left\{ \begin{array}{l} x^2 + y + z = 1 \\ y^4 + (2z - 2)y^2 + y - z + z^2 = 0 \end{array} \right. \left\{ \begin{array}{l} x + y^2 + z = 1 \\ y^4 + (2z - 2)y^2 + y - z + z^2 = 0 \end{array} \right.$$

$$\left\{ \begin{array}{l} x + y^2 + z = 1 \\ y^2 - y = z \\ 2x + z^2 = 2y + z^2 \\ z^3 + z^2 - 3z = 0 \end{array} \right.$$

$$\left\{ \begin{array}{l} x^2 + y + z = 1 \end{array} \right. \left\{ \begin{array}{l} x^2 + y + z = 1 \\ x + y^2 + z = 1 \end{array} \right. \left\{ \begin{array}{l} x^2 + y + z = 1 \\ x + y^2 + z = 1 \\ x + y + z^2 = 1 \end{array} \right.$$



$$\left\{ \begin{array}{l} x^2 + y + z = 1 \end{array} \right. \left\{ \begin{array}{l} x + y^2 + z = 1 \\ y^4 + (2z - 2)y^2 + y - z + z^2 = 0 \end{array} \right. \left\{ \begin{array}{l} x + y = 1 \\ y^2 - y = z = 0 \\ 2x + z^2 = 2y + z^2 = 1 \\ z^3 + z^2 - 3z = -1 \end{array} \right.$$

## Triangular decompositions: a task manager algorithm

A **task** is any  $[F, T]$  where  $F, T \subset K[X]$  with  $T$  regular chain. It is **solved** iff  $F = \emptyset$  and **unsolved** otherwise.

**Input:**  $F \subset K[X]$  and a variable ordering  $\leq$ .

**Output:**  $\mathcal{T}$  a triangular decomposition of  $V(F)$  by means of regular chains.

$ToDo := [[F, \emptyset]; \mathcal{T} := []$

**repeat**

**if**  $ToDo = \emptyset$  **then break**

(S)  $Tasks := \text{Select}(ToDo)$

(R)  $Results := \text{LazySolve}(Tasks)$

(U)  $(ToDo, \mathcal{T}) := \text{Update}(Results, ToDo, \mathcal{T})$

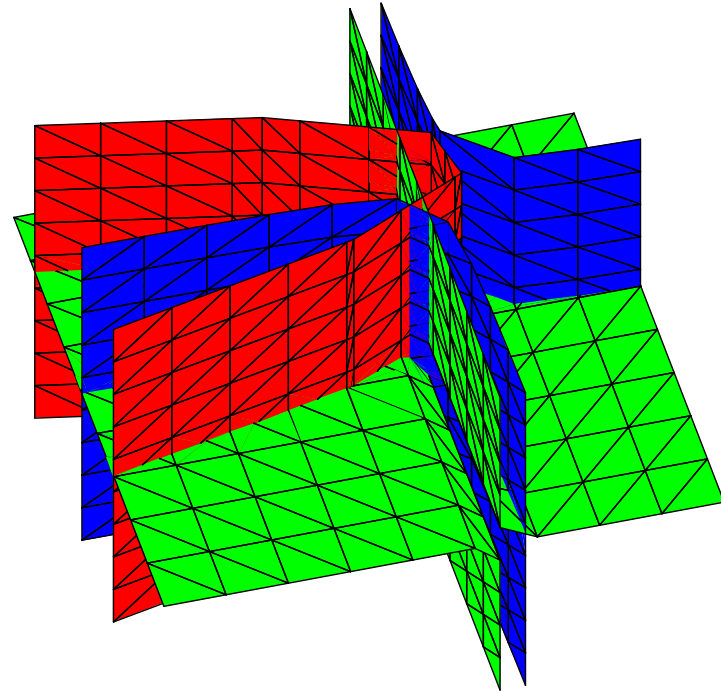
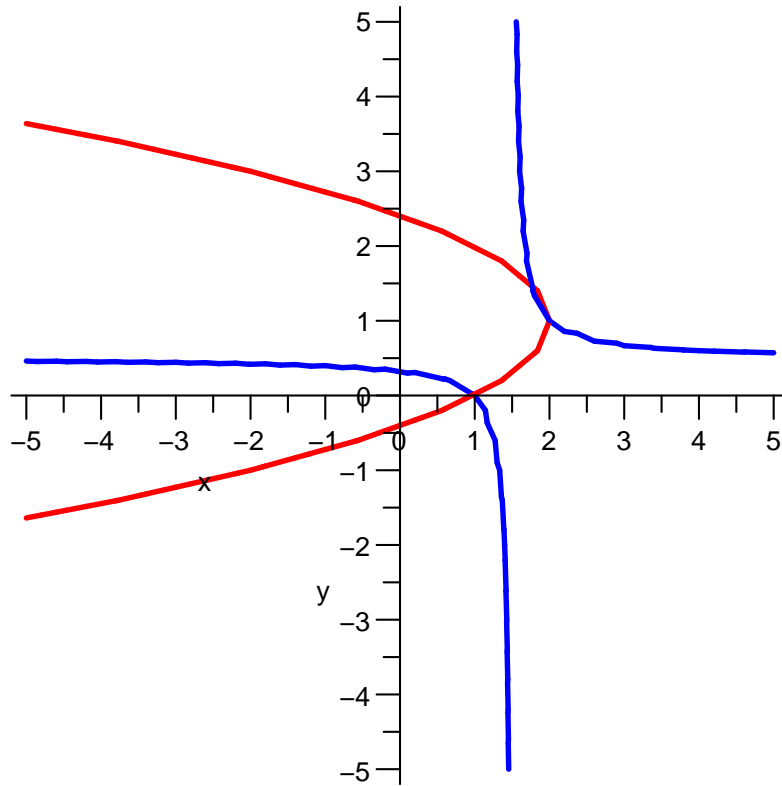
**return**  $\mathcal{T}$

$\text{LazySolve}([F, T])$  returns  $[F_1, T_1], \dots, [F_d, T_d]$  which are **less unsolved** and:

$$V(F) \cap W(T) \subseteq \bigcup_{i=1}^d Z(F_i, T_i) \subseteq V(F) \cap \overline{W(T)}.$$



## Difficulty 1: redundant and irregular tasks



The **red** and **blue** surfaces intersect on the line  $x - 1 = y = 0$  contained in the **green** plane  $x = 1$ . With the other **green** plane  $z = 0$ , they intersect at  $(2, 1, 0)$ ,  $(\frac{7}{4}, \frac{3}{2}, 0)$  but also at  $x - 1 = y = z = 0$ , which is redundant.

Initial task  $[\{f_1, f_2, f_3\}, \emptyset]$

$$f_1 = x - 2 + (y - 1)^2$$

$$f_2 = (x - 1)(y - 1) + (x - 2)y$$

$$f_3 = (x - 1)z$$

$$y = 0$$

$$x = 1$$

$$x - 1 + y^2 - 2y = 0$$

$$(2y - 1)x + 1 - 3y = 0$$

$$z = 0$$

$$z = 0$$

$$y = 0$$

$$x = 1$$

$$z = 0$$

$$y = 1$$

$$x = 2$$

$$z = 0$$

$$2y = 3$$

$$4x = 7$$

## Difficulty 2: load balancing

- How do splits occur during decompositions? Given a polynomial ideal  $\mathcal{I}$  and polynomials  $p, a, b$ , there are two rules:
  - $\mathcal{I} \longmapsto (\mathcal{I} + p, \mathcal{I} : p^\infty)$ .
  - $\mathcal{I} + \langle a b \rangle \longmapsto (\mathcal{I} + \langle a \rangle, \mathcal{I} + \langle b \rangle)$ .
- The second one is more likely to **split computations evenly**. But geometrically, it means that a component is **reducible**.
- Unfortunately, most polynomial systems  $F \subseteq Q[X]$  (both in theory and practice) are **equiprojectable**, that is they can be represented by a single regular chain.
- However, for  $F \subseteq Z/pZ[X]$  where  $p$  prime, the second rule is more likely to be used.

## Key solutions

• We rely on the Triade algorithm (MMM, 2000) for computing triangular decompositions. In this case,  $\text{LazySolve}((F, T])$  returns  $[F_1, T_1], \dots, [F_d, T_d]$

such that  $\boxed{F_i = \emptyset \iff |T_i| = |T|}$  and thus,  $\boxed{F_i \neq \emptyset \iff |T_i| > |T|}$ .

$\Rightarrow$  We **solve completely** only in the cases where dimension does not drop and **solve lazily** the other cases.

$\Rightarrow$  **Computations in lower dimension are delayed toward the end** of the solving process.

• For solving  $F \subseteq Q[X]$  we use **modular methods** (Dahan, MMM, Schost, Wu, Xie, 2005)

- For  $p$  big enough, a triangular decomposition of  $V(F)$  can be **reconstructed (= merged + lifted)** from one of  $V(F \bmod p)$ .
- The **reconstruction** is cheap (comparing to the decomposition phasis).
- This modular approach consumes less resources than the direct one.

## A parallel scheme

**Input:**  $F \subset K[X]$  and a variable ordering  $\leq$ .

**Output:**  $\mathcal{T}$  a triangular decomposition of  $V(F)$  by means of regular chains.

$ToDo := [[F, \emptyset]; \mathcal{T} := []; d := n;$

**repeat**

**if**  $ToDo = \emptyset$  **then break**

(1) **let**  $V$  be all tasks which can produce solved tasks of dimension  $d$

(2) **if**  $V \neq \emptyset$  **then**

    - lazy-solve these tasks

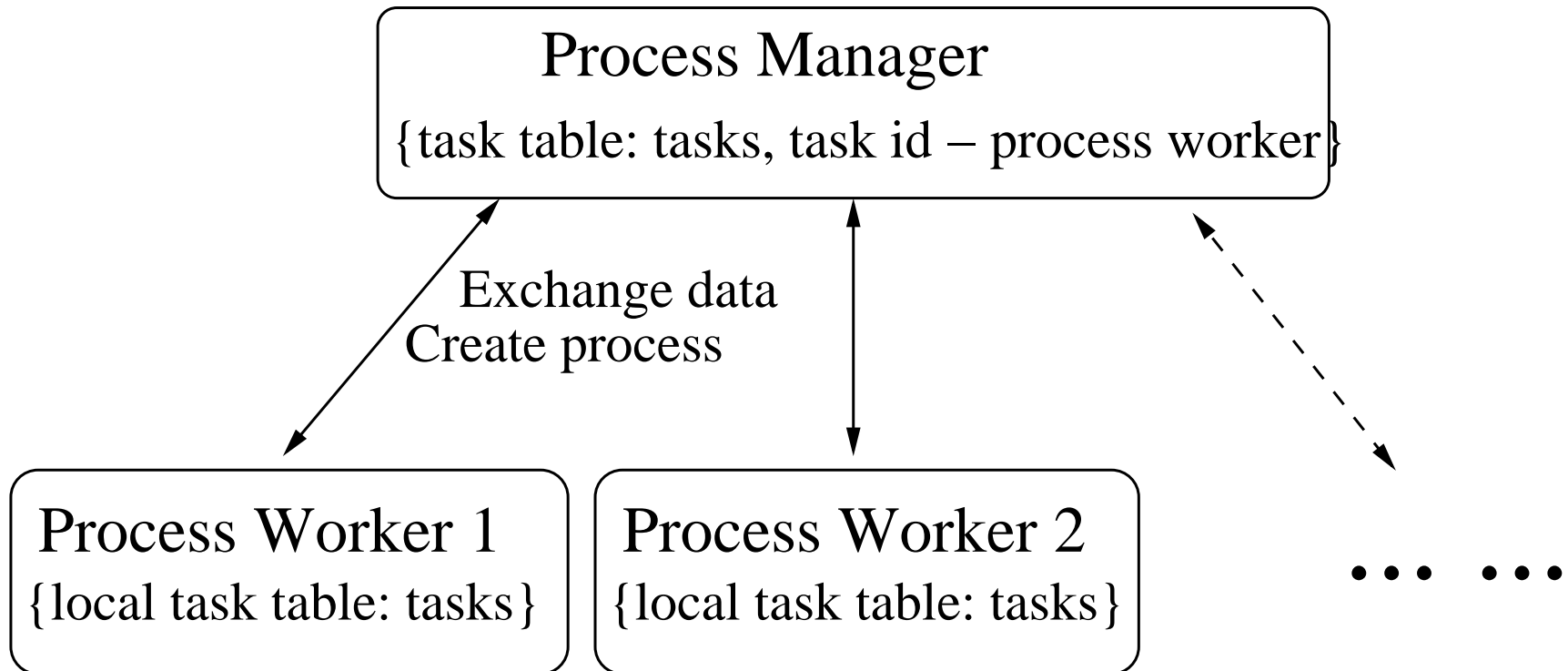
    - update  $ToDo$  and  $\mathcal{T}$

    - go to (1)

(3) **if**  $V = \emptyset$  **then**  $d := d - 1$  **and** go to (1)

**return**  $\mathcal{T}$

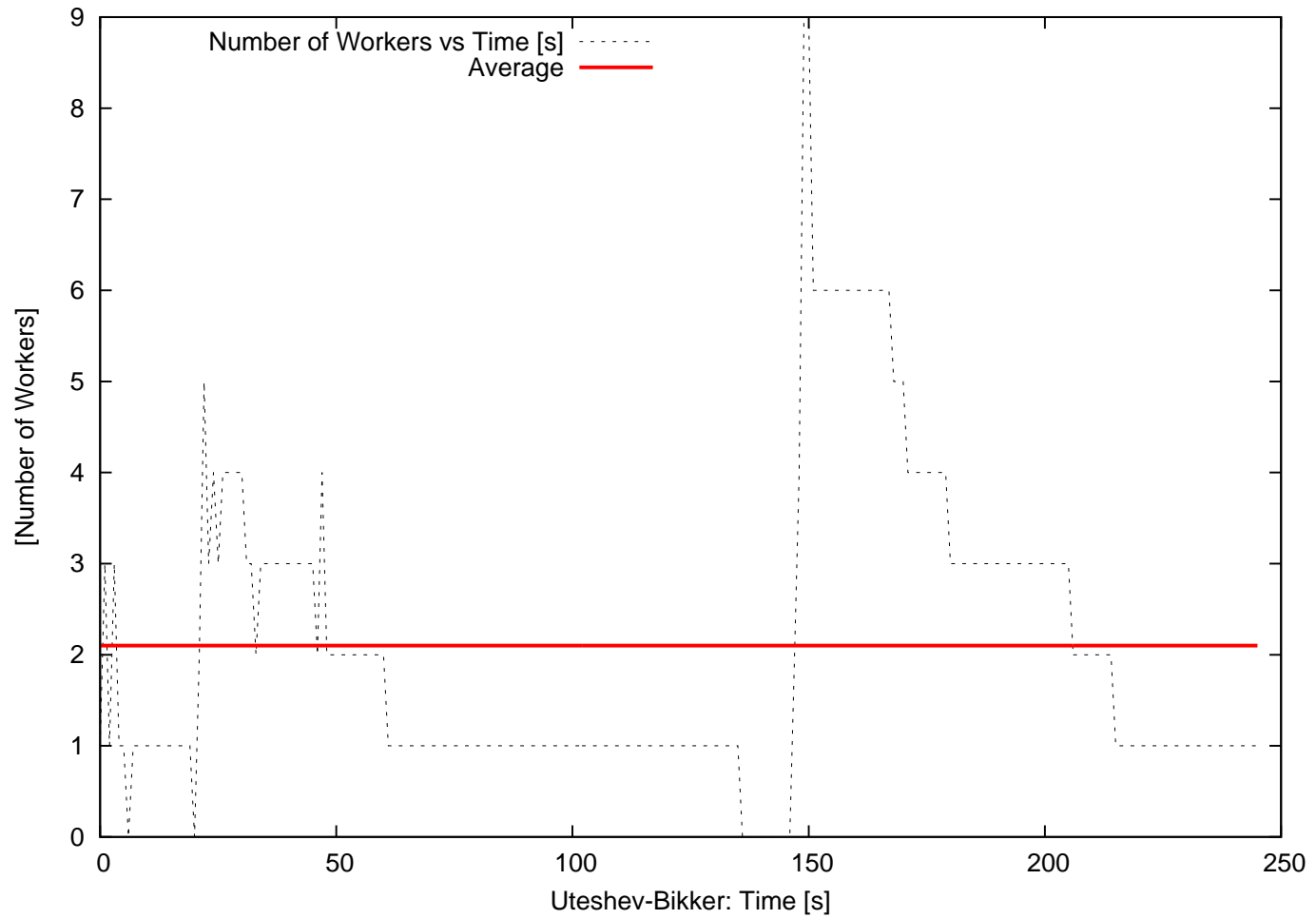
## Target implementation



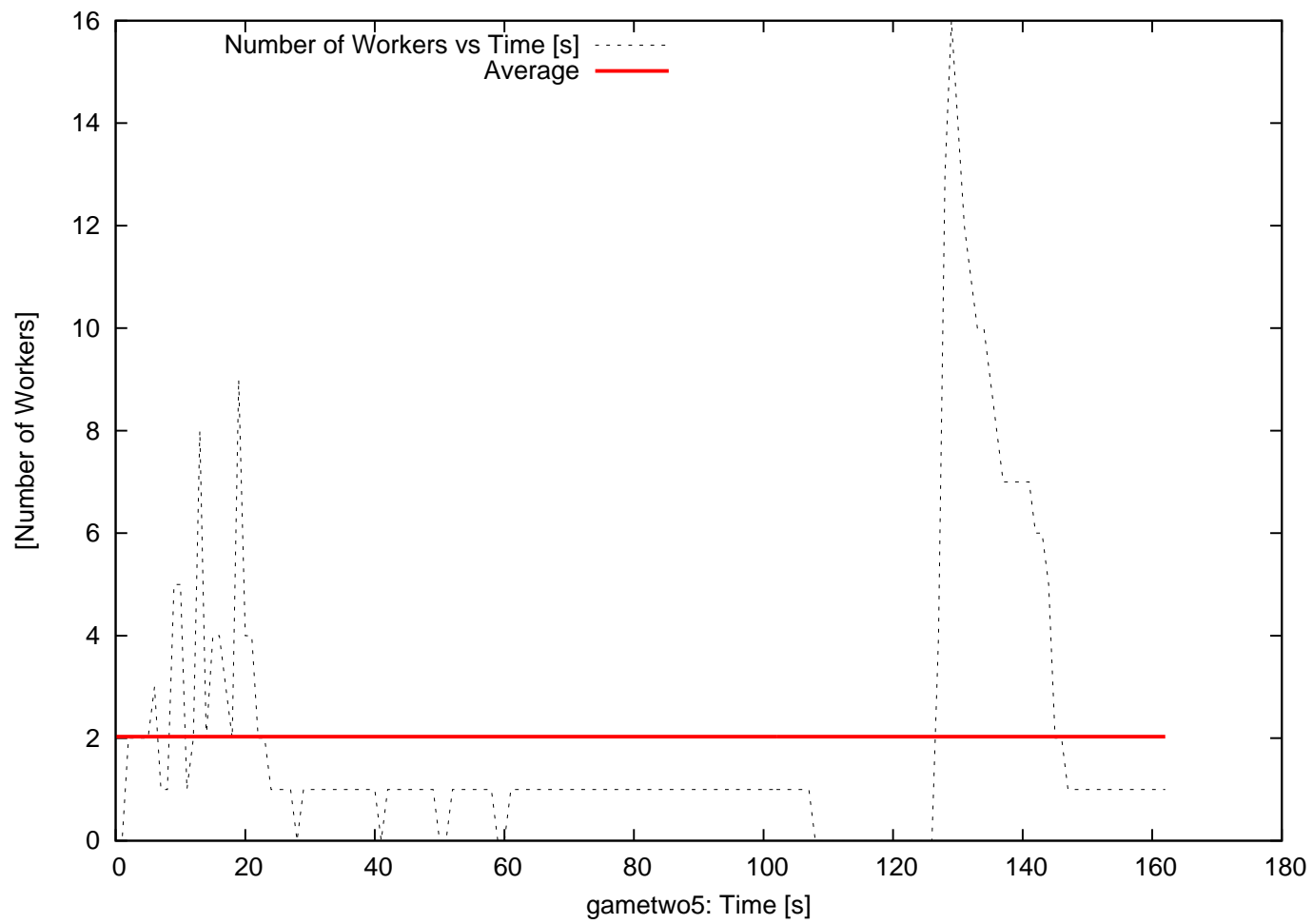
## Current implementation

- In ALDOR on a 4-processor machine using shared memory for data-communication.
- Only the output components are generated by decreasing order of dimension. (This does not hold yet for the intermediate components)  
⇒ Hence, we do not implement yet the above parallel scheme, but only an approximation of it.
- Splitting (of the 2nd kind) relies only on the *D5 Principle* and univariate polynomial factorization.
- Each *LazySolve* requires to activate a process worker, which terminates after completing this computation.  
⇒ Hence, we pay a severe penalty in data-communication and O/S calls w.r.t. our target implementation (work in progress).

# Preliminay results







## Work in progress and conclusions

- Combining the Triade algorithm and modular techniques, we have achieved successful **coarse-grain parallelization** of triangular decompositions **based on geometrical information** detected during the solving process.
- Future work:
  - Increasing the average number of working processors (by making use of multivariate factorization)
  - Reducing data-communicatio (with our target implementation scheme).
  - Making use of medium-grain parallelization (by parallelizing our GCDs/resultants).
- **Parallelizing helps removing arbitrary choices.**
- **Modular methods increase opportunities for parallelism.**