

Computing the Integer Points of a Polyhedron Algorithm

Rui-Juan Jing^{1,2} and Marc Moreno Maza^{2,3}

¹Key Laboratory of Mathematics Mechanization,
Academy of Mathematics and Systems Science,
Chinese Academy of Sciences

²University of Western Ontario, London, Ontario

³IBM Center for Advanced Studies, Markham, Ontario

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Plan

Motivation

Polyhedra

Algorithm

Summary

Motivating example: cache-line accessed by a for-loop

```
for  $i = 2$  to  $N - 1$  do  
  for  $j = 2$  to  $N - 1$  do  
     $a(i, j) = 2 * a(i, j) + a(i - 1, j) + a(i + 1, j) + a(i, j - 1) + a(i, j + 1)$ 
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Cache lines touched by this loop:

$(\sum x, y : (\exists i, j, \Delta i, \Delta j :$

$$x = (i + \Delta i - 1) \div 16 \wedge y = j + \Delta j \wedge 2 \leq i, j \leq N - 1$$

$$\wedge -1 \leq \Delta i + \Delta j, \Delta i - \Delta j \leq 1)$$

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$$\left\{ \begin{array}{l} 0 \leq (i + \Delta i - 1) / 16 - x < 1 \\ y = j + \Delta j \\ 2 \leq i, j \leq N - 1 \\ -1 \leq \Delta i + \Delta j, \Delta i - \Delta j \leq 1 \end{array} \right.$$

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Simplifying with **our code**

$$\left\{ \begin{array}{ll} -x \leq 0, & 16x - y - N \leq -3 \\ 16x - N \leq -1, & 16x + y - 2N \leq -2 \\ 1 \leq y - N \leq 0, & -N \leq -3 \end{array} \right.$$

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When $N = 500$, $(\sum x, y : 0 \leq x \leq 31 \wedge 1 \leq y \leq 500 : 1) = 16000$

Related work

1. Fourier-Motzkin elimination: computing the rational points (thus all the points) of a polyhedron in \mathbb{R}^d given by m inequalities;
Complexity: polynomial in m^d , thus **single exponential in d**
(Fourier-Motzkin algorithm; L. Khachiyan, 2009)
2. **Counting** the number of integer points of a bounded polyhedron;
Complexity: polynomial for fixed dimension.
(A. Barvinok, 1999)
3. Deciding Presburger arithmetic such as
$$(\forall x \in \mathbb{Z}) (\exists y \in \mathbb{Z}) : (y + y = x) \vee (y + y + 1 = x)$$

Complexity: **doubly exponential in d**
(Fischer & Rabin, 1974).
4. **Omega test**, can decide Presburger arithmetic;
essential in the analysis and transformation of computer programs;
(W. Pugh, 1991).
Complexity: No complexity estimate known until our work.

Our contribution

1. Based on the Omega test, we propose an algorithm for **decomposing a polyhedron** into “simpler” polyhedra, each of them having at least one integer point and good structural properties;
2. Under a mild assumption (almost always verified in practice), this decomposition can be computed within
$$O(m^{2d^2} d^{4d^3} L^{4d^3} \text{LP}(d, m^d d^4 (\log d + \log L)))$$
 bit operations, where $\text{LP}(d, H)$ is an upper bound for solving a linear program with total bit size H and d variables;
3. We implemented two versions of our algorithm in Maple:
 - ▶ one “sparse” with explicit equations and inequalities as input,
 - ▶ another with dense matrices encoding equations and inequalities.

Decomposing the integer points of a polyhedron

Example

$$\text{Input: } K_1 : \begin{cases} 3x_1 - 2x_2 + x_3 \leq 7 \\ -2x_1 + 2x_2 - x_3 \leq 12 \\ -4x_1 + x_2 + 3x_3 \leq 15 \\ -x_2 \leq -25 \end{cases}, \text{ assume } x_1 > x_2 > x_3.$$

Output: $K_1^1, K_1^2, K_1^3, K_1^4, K_1^5$ given by:

$$\begin{cases} 3x_1 - 2x_2 + x_3 \leq 7 \\ -2x_1 + 2x_2 - x_3 \leq 12 \\ -4x_1 + x_2 + 3x_3 \leq 15 \\ 2x_2 - x_3 \leq 48 \\ -5x_2 + 13x_3 \leq 67 \\ -x_2 \leq -25 \\ 2 \leq x_3 \leq 17 \end{cases}, \begin{cases} x_1 = 15 \\ x_2 = 27 \\ x_3 = 16 \end{cases}, \begin{cases} x_1 = 18 \\ x_2 = 33 \\ x_3 = 18 \end{cases}, \begin{cases} x_1 = 14 \\ x_2 = 25 \\ x_3 = 15 \end{cases}, \begin{cases} x_1 = 19 \\ x_2 = 50 + t \\ x_3 = 50 + 2t \\ -25 \leq t \leq -16. \end{cases}$$

Decomposing the integer points of a polyhedron

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- ▶ An integer point solves K_1 iff it solves either $K_1^1, K_1^2, K_1^3, K_1^4$ or K_1^5 .
- ▶ Each of $K_1^1, K_1^2, K_1^3, K_1^4, K_1^5$ has at least one integer point.
- ▶ For each K_1^i , each integer point in the projection can be lifted to an integer point in the polyhedron.

Plan

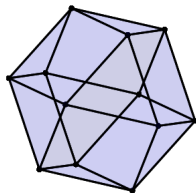
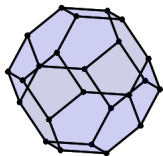
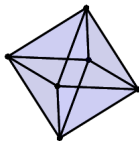
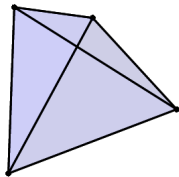
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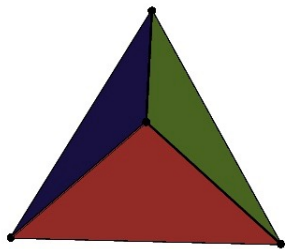
Summary

How polyhedra look like?



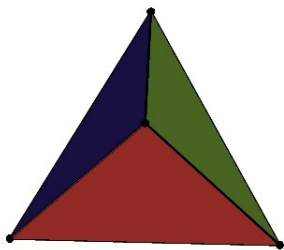
Polyhedra geometrically

- ▶ \mathbb{R}^d : d -dim Euclidean space
- ▶ for $\mathbf{a} \in \mathbb{R}^d$, $b \in \mathbb{R}$, the set $P = \{\mathbf{x} \in \mathbb{R}^d \mid \mathbf{a}^T \mathbf{x} = b\}$ is a *hyperplane* and,
- ▶ $H = \{\mathbf{x} \in \mathbb{R}^d \mid \mathbf{a}^T \mathbf{x} \leq b\}$ is a *closed half-space*.



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- ▶ A *polyhedron* K is the intersection of finitely many closed half-spaces H_1, \dots, H_m , that is, $K = \bigcap_{i=1}^m H_i$
- ▶ This intersection is *irredundant* if $K \neq \bigcap_{i=1, j \neq i}^m H_i$ for all $1 \leq j \leq m$
- ▶ P_i : hyperplane associated with H_i .
- ▶ Then, any $\emptyset \neq \left(\bigcap_{i \in I} P_i \right) \cap K$ is a *face* of K , for $I \subseteq \{1, \dots, m\}$

Polyhedra algebraically

Consider $K_0 = \bigcap_{i=1}^6 H_i$ with

$$\left\{ \begin{array}{l} H_1 : \quad 2x + 3y - 4z + 3w \leq 1 \\ H_2 : \quad -2x - 3y + 4z - 3w \leq -1 \\ H_3 : \quad -13x - 18y + 24z - 20w \leq -1 \\ H_4 : \quad -26x - 40y + 54z - 39w \leq 0 \\ H_5 : \quad -24x - 38y + 49z - 31w \leq 5 \\ H_6 : \quad 54x + 81y - 109z + 81w \leq 2 \end{array} \right.$$

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Remark

Any polyhedron can be represented by

$$\left\{ \begin{array}{l} \mathbf{A}^= \mathbf{x} = \mathbf{b}^= \\ \mathbf{A}^{\leq} \mathbf{x} \leq \mathbf{b}^{\leq} \end{array} \right.$$

- ▶ where $\mathbf{x} = [x_1, \dots, x_d]^T$,
 $\mathbf{A}^= \in \mathbb{R}^{m_1 \times d}$, $\mathbf{b}^= \in \mathbb{R}^{m_1}$,
 $\mathbf{A}^{\leq} \in \mathbb{R}^{m_2 \times d}$, $\mathbf{b}^{\leq} \in \mathbb{R}^{m_2}$, and
- ▶ $\mathbf{A}^{\leq} \mathbf{x} \leq \mathbf{b}^{\leq}$ no implicit equations.

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Consider the polyhedron K of \mathbb{R}^4 given below ($\mathbf{Ax} \leq \mathbf{b}$):

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Algorithm-IntegerNormalize

Procedure 1- IntegerNormalize($\mathbf{Ax} \leq \mathbf{b}$):

1. Solve integer solutions for (implicit) equations:
 - ▶ Tools: Hermite normal form;
 - ▶ Return $\mathbf{x} = \mathbf{Pt} + \mathbf{q}$, where \mathbf{t} is a new unknown vector with less length than \mathbf{x} .
2. Substitute $\mathbf{x} = \mathbf{Pt} + \mathbf{q}$ into $\mathbf{Ax} \leq \mathbf{b}$ and remove redundant inequalities:
 - ▶ $\mathbf{cx} \leq d$ is implied by $\mathbf{Ax} \leq \mathbf{b} \iff \sup\{-(\mathbf{cx} - d) \mid \mathbf{Ax} \leq \mathbf{b}\} = 0$;
 - ▶ Return $\mathbf{Mt} \leq \mathbf{v}$.

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 - ▶ Return $\mathbf{Mt} \leq \mathbf{v}$.

In our example, implicit equation: $2x + 3y - 4z + 3w = 1$
the systems $\mathbf{x} = \mathbf{Pt} + \mathbf{q}$ and $\mathbf{Mt} \leq \mathbf{v}$ are given by:

$$\begin{cases} x = -3t_1 + 2t_2 - 3t_3 + 2 \\ y = 2t_1 + t_3 - 1 \\ z = t_2 \\ w = t_3 \end{cases} \quad \text{and} \quad \begin{cases} 3t_1 - 2t_2 + t_3 \leq 7 \\ -2t_1 + 2t_2 - t_3 \leq 12 \\ -4t_1 + t_2 + 3t_3 \leq 15 \\ -t_2 \leq -25 \end{cases} .$$

Algorithm-DarkShadow

- ▶ Consider a polyhedron K :

$$\begin{cases} a_{11}t_1 + \dots + a_{1d}t_d \leq b_1 \\ \vdots \\ a_{m1}t_1 + \dots + a_{md}t_d \leq b_m \end{cases}$$

- ▶ We aim at eliminating t_1 , so we consider 2 inequalities in t_1 .

- ▶ one where $a_{i1} > 0$, called **upper bound**:

$$l_i : a_{i1}t_1 + \dots + a_{id}t_d \leq b_i$$

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Fourier-Motzkin elimination: real projection r_{ij} :

$$-a_{j1}(a_{i2}t_2 + \dots + a_{id}t_d) + a_{i1}(a_{j2}t_2 + \dots + a_{jd}t_d) \leq -a_{j1}b_i + a_{i1}b_j.$$

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Omega test: dark projection d_{ij} (translates r_{ij} towards the center of K):

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Lemma

For any integer point $(t_2, \dots, t_d) \in \mathbb{Z}^{d-1}$ satisfying d_{ij} , there exists at least one integer $t_1 \in \mathbb{Z}$ satisfying both l_i and l_j .

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Lemma

For any integer point $(t_2, \dots, t_d) \in \mathbb{Z}^{d-1}$ satisfying d_{ij} , there exists at least one integer $t_1 \in \mathbb{Z}$ satisfying both l_i and l_j .

Note that this property does not apply to r_{ij} .

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Let $S^{<t_1}$ consist of the inequalities defining K without t_1 .

- ▶ Combining all the real projections with $S^{<t_1} \Rightarrow$ **real shadow**
- ▶ Combining all the dark projections with $S^{<t_1} \Rightarrow$ **dark shadow**

Example

Continue with above polyhedron K_1 :

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Example

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Real Shadow R_1 w.r.t. t_1 :

$$\begin{cases} 2t_2 - t_3 \leq 50 \\ -5t_2 + 13t_3 \leq 73 \\ -t_2 \leq -25 \end{cases} .$$

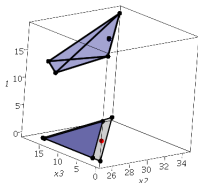
Dark Shadow D_1 w.r.t. t_1 :

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Example

Continue with above polyhedron K_1 :

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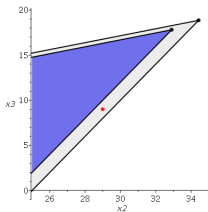


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$(t_2, t_3) = (29, 9) \in R_1 \setminus D_1$ does not extend to an integer point of K_1 .
Indeed, plugging $(t_2, t_3) = (29, 9)$ into K_1 yields $\frac{37}{2} \leq t_1 \leq \frac{56}{3}$.

Algorithm-Grey shadow

Procedure 3- GreyShadow($\mathbf{M}t \leq \mathbf{v}$)

Technical details

Check the hyperplans which may contain integer points in the grey shadow $(R_1 \setminus D_1)$:

- ▶ for each upper bound $l_i : a_{i1}t_1 + \dots + a_{id}t_d \leq b_i$ and lower bound $l_j : a_{j1}t_1 + \dots + a_{jd}t_d \leq b_j$ of t_1 in K_1 , let $B = \lfloor \frac{-a_{i1}a_{j1}-a_{i1}+a_{j1}}{a_{i1}} \rfloor$;

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Lemma

L : the maximum absolute value of a coefficient in K_1 ;

m : the number of inequalities representing K_1 .

Then, the number of grey shadow parts of K_1 w.r.t. t_1 is at most mL .

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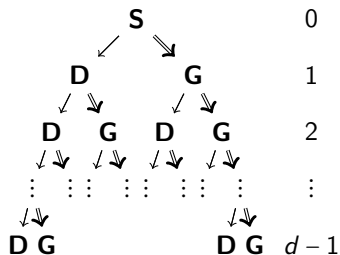
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Choose another pair of upper bound and lower bound, repeat.

Outline of the algorithm



- ▶ **S**: input system, **D**: dark shadow, **G**: grey shadow.
- ▶ \rightarrow : one path of dark shadow, \Rightarrow : many pathes of grey shadow.
- ▶ With **N** being either **D** or **G**, each path in the tree has the form $\mathbf{S} \rightarrow \mathbf{N}_1 \rightarrow \mathbf{N}_2 \rightarrow \dots \rightarrow \mathbf{N}_r$ for some positive integer $r \leq d-1$.
- ▶ For example, the leftmost path is

$$\mathbf{S} \rightarrow \mathbf{D}_1 \rightarrow \mathbf{D}_2 \rightarrow \dots \rightarrow \mathbf{D}_r$$

Plan

Motivation

Polyhedra

Algorithm

Summary

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- ▶ We have presented an algorithm for computing the **integer points** of a polyhedron, based on the **Omega test** procedure proposed by W. Pugh.
- ▶ This is done by **decomposing** the input polyhedron into simpler polyhedra, each of them with at least one integer point.
- ▶ We improve it by making use of **Hermite normal form** and controlling the size of the intermediate coefficients.