

Real Root Isolation of Regular Chains.

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Plan

- 1 Real Root Isolation and Regular Chains
- 2 The classical Vincent-Collins-Akritis Algorithm
- 3 The Vincent-Collins-Akritis Algorithm modulo a regular chain
- 4 Implementation Issues
- 5 Experimentation
- 6 Conclusion

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Real Root Isolation

Goal

Isolate the real roots of a zero-dimensional algebraic variety $V \subset \mathbb{C}^n$ given by a **regular chain** C .

Example

$$C = \{x^2 - 2, xy^2 - 1\}$$

EXACT REAL ROOTS:

$$\{x_1 = \sqrt{2}, y_1 = \sqrt{\frac{\sqrt{2}}{2}}\} \text{ and } \{x_2 = \sqrt{2}, y_2 = -\sqrt{\frac{\sqrt{2}}{2}}\}$$

ISOLATED ROOTS:

$$\{x_1 \in [1.41, 1.42], y_1 \in [0.84, 0.85]\} \text{ and } \\ \{x_2 \in [1.41, 1.42], y_2 \in [-0.85, -0.84]\}$$

ENCODED ROOTS:

$$\text{box}_1 = [C, [1.41, 1.42], [0.84, 0.85]] \text{ and } \\ \text{box}_2 = [C, [1.41, 1.42], [-0.84, -0.85]].$$

Root Isolation

Box

A n -box is of the form $B = I_1 \times \cdots \times I_n$ where each I_i is

- either $]a, b[$ for some $a, b \in \mathbb{Q}$ with $a < b$; then $|I_i| := b - a$,
- or $\{a\}$ for some $a \in \mathbb{Q}$; then $|I_i| = 0$.

The *width* of B , denoted by $|B|$, is the max of the $|I_i|$.

Isolation

Let $V \subset \mathbb{C}^n$ be a zero-dimensional variety. A list B_1, \dots, B_t of n -boxes is a *box-decomposition* of $V \cap \mathbb{R}^n$ if

- each point of $V \cap \mathbb{R}^n$ lies in exactly one B_i ,
- $B_i \cap B_j = \emptyset$ whenever $i \neq j$,
- $|B_i|$ can be made arbitrary small for all i .

Zero-dimensional Regular Chains

Definition

$T \subset \mathbb{Q}[x_1 < \dots < x_n] \setminus \mathbb{Q}$ is a *zero-dimensional regular chain* if

- $T = \{T_1(x_1), T_2(x_1, x_2), \dots, T_n(x_1, \dots, x_n)\}$,
- $\text{lc}(T_i, x_i)$ is invertible modulo $\langle T_1, \dots, T_{i-1} \rangle$ for $1 < i \leq n$,

Additional Properties

- 1 *Reduced*: $\deg(T_i, x_j) < \deg(T_j, x_j)$ for $1 \leq j < i \leq n$.
- 2 *Squarefree*: T_i and $\frac{\partial T_i}{\partial x_i}$ are relatively prime modulo $\langle T_1, \dots, T_{i-1} \rangle$ for $1 \leq i \leq n$,
- 3 *Normalized*: $\text{lc}(T_i, x_i) = 1$ for $1 \leq i \leq n$.

Comment

We require **squarefreeness** to ensure termination of our isolation process and speed-up sub-algorithms.

Three Fundamental Theorems

Descartes

Let $f = a_d x^d + \dots + a_0 \in R[x]$ with $a_d \neq 0$. Let v be the number of sign changes in a_d, \dots, a_0 and let r be the number of positive real roots of f . Then, there exists $m \geq 0$ such that we have $r = v - 2m$.

Sturm

Let $f \in \mathbb{R}[x]$ be a square-free polynomial and let $a, b \in \mathbb{R}$ s.t. $a < b$ and $f(a)f(b) \neq 0$. Let $f_0 = f, f_1, \dots, f_s$ be a Sturm sequence for f on $[a, b]$. Then, the number of distinct roots of f in $[a, b]$ is given by $V(a) - V(b)$.

Yang, Hou and Zeng

Let $f = a_d x^d + \dots + a_0 \in R[x]$ with $a_d \neq 0$. Let $D = D_1, D_2, \dots, D_d$ be the discriminant sequence of f and L its revised sign list. Let ν be the number of sign changes in L and ℓ that of non-zero entries in L . Then, the number of distinct real roots of f equals $\ell - 2\nu$.

Real Root Isolation Algorithms (1/2)

For polynomials in $\mathbb{Q}[x]$

- The (independent) works of Vincent and Uspensky turn Descartes rule of signs into an algorithm for RRI.
- Rouillier and Zimmermann (2003) have designed a memory-efficient of it.
- Akritas et al. (2006, 2007) have further develop Vincent's work.

For univariate with real algebraic number coefficients

- Rioboo (1992) using Sturm Sequences and isolation intervals.
- Collins, Krandick, Johnson (2002, 1887) using Descartes rule of signs and interval arithmetic.

Real Root Isolation Algorithms (2/2)

For zero-dimensional multivariate systems

Various techniques are employed to reduce to the univariate case

- 1 *RUR*: (Rouillier, AAEEC 1999)
- 2 *Polyhedron Algebra*: (Mourrain & Pavone, Tech. Rep. 2005)
- 3 *Triangular Sets*:
 - (Cheng, Gao & Yap, ISSAC 2007)
 - (Lu, He, Luo & Pan, SNC 2005)
 - (Xia & Zhang, Comput Math Appl 2006)

These methods:

- rely on sleeve of polynomials on an interval,
- use big floats or interval arithmetic,
- do **not** use algebraic operations (invertibility test, GCD computation) modulo a regular chain.

Our approach

Main idea

- Adapt Vincent-Collins-Akritas to $(\mathbb{Q}[x_1, \dots, x_i]/\langle T \rangle)[x_{i+1}]$ where T is a 0-dim. squarefree regular chain.
- Deduce a RealRootIsolate command for 0-dim. regular chains.

Challenge

- $L_i := \mathbb{Q}[x_1, \dots, x_i]/\langle T \rangle$ may not be a field and
- we need to evaluate signs of elements in L_i

Solution

- Combine interval arithmetic and invertibility test modulo $\langle T \rangle$.
- invertibility test shoots troubles in sign determination.
- (Rioboo 1992) uses a similar technique but in for univariate polynomials and with Sturm sequences.

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VCA algorithm

Algorithm 1 $VCA(p,]a, b[$

Input: $p \in \mathbb{Q}[x]$ squarefree and $a < b$ rational.

Output: an interval decomposition of $V(p) \cap]a, b[$.

- 1: $nsv \leftarrow \text{RootNumberBound}(p,]a, b[$
 - 2: **if** $nsv = 0$ **then return** \emptyset
 - 3: **else if** $nsv = 1$ **then return** $]a, b[$
 - 4: **else**
 - 5: $m \leftarrow (a + b)/2$ $res \leftarrow \emptyset$
 - 6: **if** $p(m) = 0$ **then** $res \leftarrow \{\{m\}\}$
 - 7: {Next line ensures the roots are sorted increasingly}
 - 8: **return** $VCA(p,]a, m[) \cup res \cup VCA(p,]m, b[$
-

The RootNumberBound Algorithm

Algorithm 2 RootNumberBound($p,]a, b[$)

Input: $p \in \mathbb{Q}[x]$ and $a < b$ rational

Output: a bound on the number of roots of p in the interval $]a, b[$

1: $\bar{p} \leftarrow (x + 1)^d p \left(\frac{ax+b}{x+1} \right)$ where d is the degree of p , and denote

$$\bar{p} = \sum_{i=0}^d a_i x^i$$

2: $a'_e, \dots, a'_0 \leftarrow$ the sequence obtained from a_d, \dots, a_0 by removing zero coefficients

3: **return** the number of sign variations in the sequence a'_e, \dots, a'_0

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Invertibility Test

Algorithm 3 CheckZeroDivisor(p, T)

Input: $T \subset \mathbb{Q}[x_1, \dots, x_n]$ a 0-dim regular chain and $p \in \mathbb{Q}[x_1, \dots, x_n]$

Output: If p is invertible modulo T , then the algorithm terminates normally. Otherwise, an exception is thrown exhibiting $t \geq 2$ regular chains T_1, \dots, T_t such that $\langle T \rangle = \cap \langle T_i \rangle$ and $\sum_{i=1}^t \deg(T_i) = \deg(T)$.

1: $T_1, \dots, T_t \leftarrow \text{Regularize}(p, T)$

2: **if** p belongs to at least one $\langle T_i \rangle$ **then throw exception**(T_1, \dots, T_t)

DC Condition and Task

DC Condition

Let $B = I_1 \times \cdots \times I_t$ be an s -box and $T = \{p_1, \dots, p_s\} \subset \mathbb{Q}[x_1, \dots, x_s]$ be a 0-dim reg. chain. (B, T) satisfies the *Dichotomy Condition (DC)* if

- one and only one real root of T lies in B
- if $I_1 =]a, b[$ then $p_1(x_1 = a)p_1(x_1 = b) < 0$ holds
- if $I_k =]a, b[$, then $\text{EvalBox}(p_k(x_k = a), B)$, $\text{EvalBox}(p_k(x_k = b), B)$ do not meet 0 and have opposite signs, for all $2 \leq k \leq s$.

Task

Let T and B be as before such that (B, T) satisfies **DC**. Let $p \in \mathbb{Q}[x_1, \dots, x_{s+1}]$ such that $T \cup p$ is a regular chain. Let $a < b$ be in \mathbb{Q} . Then $\mathcal{M} = \text{TASK}(p,]a, b[, B, T)$ is called a task.

The solution of \mathcal{M} denoted by $V_t(\mathcal{M})$ is defined as $V(T \cup \{p\}) \cap (B \times]a, b[)$ (i.e. the real solutions of $T \cup \{p\}$ which prolong the real root in B and whose x_{s+1} -component lies in $]a, b[$).

VCA Algorithm Modulo a Regular Chain

Algorithm 4 SolveTask(\mathcal{M})

Input: a task $\mathcal{M} = \text{TASK}(p,]a, b[, B, T)$ where T is a 0-dim squarefree regular chain of $\mathbb{Q}[x_1, \dots, x_s]$.

- 1: $nsv, B' \leftarrow \text{RootNumberBound}(\mathcal{M})$
 - 2: **if** $nsv = 0$ **then return** \emptyset
 - 3: **else if** $nsv = 1$ **then**
 - 4: $B'' \leftarrow B' \times]a, b[$
 - 5: refine B'' until $(B'', T \cup \{p\})$ satisfies **DC**
 - 6: **return** $\{B''\}$
 - 7: **else**
 - 8: $m \leftarrow (a + b)/2$ $res \leftarrow \emptyset$ $p' \leftarrow p(x_{s+1} = m)$
 - 9: **if** $p' \in \langle T \rangle$ **then** $res \leftarrow \{B' \times \{m\}\}$ **else** $\text{CheckZeroDivisor}(p', T)$
 - 10: **return** $res \cup \{\text{TASK}(p,]a, m[, B', T), \text{TASK}(p,]m, b[, B', T)\}$
-

The RootNumberBound Algorithm

Algorithm 5 RootNumberBound(\mathcal{M})

Input: a task $\mathcal{M} = \text{TASK}(p,]a, b[, B, T)$ where $T \subset \mathbb{Q}[x_1, \dots, x_s]$.

Output: (nsv, B') such that $B' \subset B$, (B', T) satisfies **DC**, and nsv is a bound on the cardinal of $V_t(\mathcal{M})$. The bound is exact if $nsv \in \{0, 1\}$.

- 1: $\bar{p} \leftarrow (x_{s+1} + 1)^d p \left(x_{s+1} = \frac{ax_{s+1} + b}{x_{s+1} + 1} \right)$ with $d = \text{mdeg}(p)$
 - 2: denote $\bar{p} = \sum_{i=0}^d a_i x_{s+1}^i$
 - 3: $a'_e, \dots, a'_0 \leftarrow$ the sequence obtained from a_d, \dots, a_0 by removing the a_i belonging to $\langle T \rangle$
 - 4: **for all** a'_i **do** CheckZeroDivisor(a'_i, T)
 - 5: $B' \leftarrow B$
 - 6: **while** there is an a'_i such that $0 \in \text{EvalBox}(a'_i, B')$ **do** $B' = \text{RefineBox}(B', T)$
 - 7: **return** the number of sign variations of the sequence
 $\text{EvalBox}(a'_e, B'), \text{EvalBox}(a'_{e-1}, B'), \dots, \text{EvalBox}(a'_0, B')$
-

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Implementation Issues

Tricks currently used

- Fast Taylor Shift (von zur Gathen & Gerhard, ISSAC 2007)
- Horner's rule for evaluating a polynomial on a box

Work in progress

- fast arithmetic techniques for $\text{CheckZeroDivisor}(p, T)$ and testing $p \in \langle T \rangle$.
- Subproduct tree techniques for multiple calls to CheckZeroDivisor
- Greedy algorithms for optimizing Horner's rule
- Using floating-point number arithmetic (MPFR library) for interval arithmetic.

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Special examples

nql- n - d examples

- Suggested by Fabrice Rouillier
- $x_1^d - 2 = 0$, $x_i^d + x_i^{d/2} - x_{i-1} = 0$ for $2 \leq i \leq n$ for some even degree d .
- This is a zero-dimensional regular chain.
- The algorithm RealRootIsolate solves it easily since the degrees are distributed evenly among the equations.
- A similar example is simple-nql- n - d defined by $x_1^d - 2 = 0$, $x_i^d - x_{i-1} = 0$ for $2 \leq i \leq n$. The degree of the rational univariate representation is also roughly d^n . For the example simple-nql-20-30, d^n is around 10^{29} .

nld- d - n examples

- n equations of the form
$$x_1 + \cdots + x_{i-1} + x_i^d + x_{i+1} + \cdots + x_n - 1 = 0 \text{ for } 1 \leq i \leq n.$$
- Triangularize tend to split it into many branches, even though the equiprojectable decomposition consists of a few components (generally 2 or 3).
- For System nld-9-3, which has degree 729, the command Triangularize produces 16 components where the largest coefficient has size 20 digits.
- Whereas there are 3 equiprojectable components where most coefficients have more than 1,000 digits.

Comparison with RootFinding[Isolate]

	Sys	v/e/s	Rf-1	Rf-2	Tr	Is/10
1	4-body-homog	3/3/7	0.31	0.32	1.6	11
2	5-body-homog	3/3/11	0.31	0.36	3.1	32
3	Caprasse	4/4/18	0.13	0.12	1.2	2.9
4	circles	2/2/22	0.89	0.9	0.55	26
5	cyclic-5	5/5/10	0.4	0.4	2.4	4.6
6	neural-network	4/4/22	1	1	0.81	18
7	nld-9-3	3/3/7	1785	1777	39	43
8	nld-10-3	3/3/8	>2000	>2000	26	148
9	nql-10-4	10/10/2	>2000	>2000	0.33	3.2
10	nql-15-2	15/15/2	>2000	>2000	0.36	5.8
11	p3p-special	5/5/24	0.41	0.46	0.23	23
12	r-5	5/5/1	1.6	1.6	0.43	<0.1
13	r-6	6/6/1	>2000	>2000	0.96	<0.1
14	Rose	3/3/18	0.63	0.67	0.72	39
15	simple-nql-20-30	20/20/2	>2000	>2000	0.57	28

Different Strategies

Sys	Strategy 1		Strategy 2		Strategy 3			
	Tr	Is/10	Tr/No	Is/10	Tr	Is/ ∞	$\infty/5$	5/10
1	1.6	11	6.2	11	1.5	3.4	4	4.1
2	3.1	32	38	43	3.2	9.4	11	12
3	1.2	2.9	1.5	2	1.2	0.52	1.6	1.4
4	0.55	26	1.1	26	0.59	16	4.6	4.5
5	2.4	4.6	3.6	1.4	2.5	0.67	3.9	1.8
6	0.81	18	1.2	15	0.87	4.5	7.7	7
7	39	43	121	70	40	45	0.34	0.29
8	26	148	370	308	25	148	8.1	8.1
9	0.33	3.2	0.61	3.3	0.34	0.92	0.62	0.83
10	0.36	5.8	0.65	5.7	0.33	3.1	1.3	1.9
11	0.23	23	0.69	31	0.24	6.4	8.2	9
12	0.43	<0.1	0.49	<0.1	0.37	<0.1	<0.1	<0.1
13	0.96	<0.1	1.2	<0.1	0.98	<0.1	<0.1	<0.1
14	0.72	39	1.1	59	0.71	5	22	20
15	0.57	28	0.88	28	0.63	65	2.8	0.33

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Conclusion

- We have adapted the Vincent-Collins-Akritas Algorithm to work modulo a zero-dimensional regular chain
- This provides a way for isolating the real roots of zero-dimensional systems.
- In our context, it is easy to prescribe the values of some variables and take it into account during the isolation process.
- We have realized a preliminary, non-optimized implementation in Maple interpreted code.
- For certain degree configurations (non Shape Lemma systems) it can outperform optimized implementation written in C.
- There is a large room for optimizing our VCA algorithm and its implementation.