Introduction to Multicore Programming

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CS 3101

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Introduction to Multicore Programming

CS 3101 1 / 49



Multi-core Architecture

- Multi-core processor
- CPU Cache
- CPU Coherence

2 Concurrency Platforms

- An overview of Cilk++
- Race Conditions and Cilkscreen
- MMM in Cilk++

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Plan

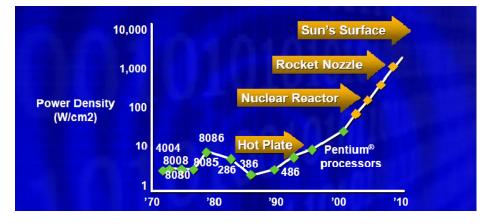
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CS 3101 4 / 49

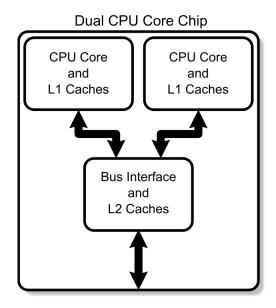
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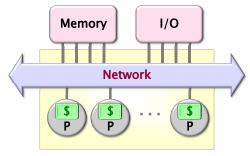
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Chip Multiprocessor (CMP)

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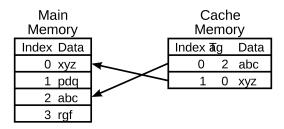
Multi-core processor

- A multi-core processor is an integrated circuit to which two or more individual processors (called cores in this sense) have been attached.
- In a many-core processor the number of cores is large enough that traditional multi-processor techniques are no longer efficient.
- Cores on a multi-core device can be coupled tightly or loosely:
 - may share or may not share a cache,
 - implement inter-core communications methods or message passing.
- Cores on a multi-core implement the same architecture features as single-core systems such as instruction pipeline parallelism (ILP), vector-processing, SIMD or multi-threading.
- Many applications do not realize yet large speedup factors: parallelizing algorithms and software is a major on-going research area.

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CPU Cache

CPU Cache (1/7)

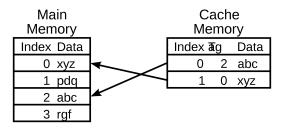


- A CPU cache is an auxiliary memory which is smaller, faster memory than the main memory and which stores copies of of the main memory locations that are expectedly frequently used.
- Most modern desktop and server CPUs have at least three independent caches: the data cache, the instruction cache and the translation look-aside buffer.

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CPU Cache

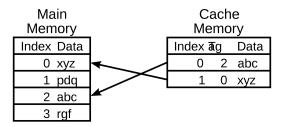
CPU Cache (2/7)



- Each location in each memory (main or cache) has
 - a datum (cache line) which ranges between 8 and 512 bytes in size, while a datum requested by a CPU instruction ranges between 1 and 16.
 - a unique index (called address in the case of the main memory)
- In the cache, each location has also a tag (storing the address of the corresponding cached datum).

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CPU Cache (3/7)

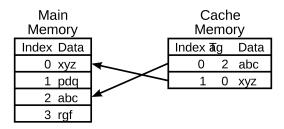


• When the CPU needs to read or write a location, it checks the cache:

- if it finds it there, we have a cache hit
- if not, we have a cache miss and (in most cases) the processor needs to create a new entry in the cache.
- Making room for a new entry requires a replacement policy: the Least Recently Used (LRU) discards the least recently used items first; this requires to use age bits.

CPU Cache

CPU Cache (4/7)

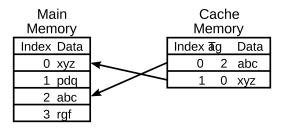


• Read latency (time to read a datum from the main memory) requires to keep the CPU busy with something else:

out-of-order execution: attempt to execute independent instructions arising after the instruction that is waiting due to the cache miss

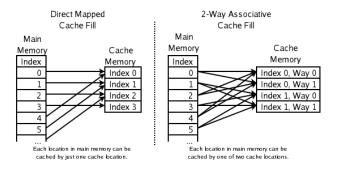
hyper-threading (HT): allows an alternate thread to use the CPU

CPU Cache (5/7)



- Modifying data in the cache requires a write policy for updating the main memory
 - write-through cache: writes are immediately mirrored to main memory
 - write-back cache: the main memory is mirrored when that data is evicted from the cache
- The cache copy may become out-of-date or stale, if other processors modify the original entry in the main memory.

CPU Cache (6/7)

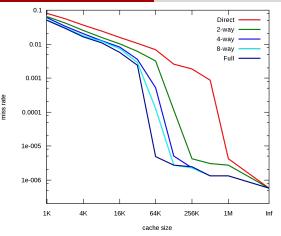


- The replacement policy decides where in the cache a copy of a particular entry of main memory will go:
 - fully associative: any entry in the cache can hold it
 - direct mapped: only one possible entry in the cache can hold it
 - N-way set associative: N possible entries can hold it

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Multi-core Architecture

CPU Cache



- Cache Performance for SPEC CPU2000 by J.F. Cantin and M.D. Hill.
- The SPEC CPU2000 suite is a collection of 26 compute-intensive, non-trivial programs used to evaluate the performance of a computer's CPU, memory system, and compilers (http://www.spec.org/osg/cpu2000).

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Cache Coherence (1/6)

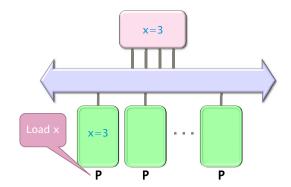


Figure: Processor P_1 reads x=3 first from the backing store (higher-level memory)

CS 3101 16 / 49

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Cache Coherence (2/6)

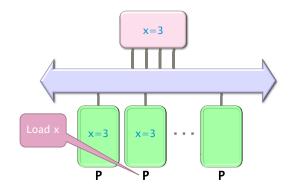


Figure: Next, Processor P_2 loads x=3 from the same memory

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Cache Coherence (3/6)

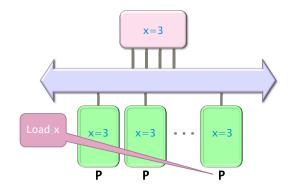


Figure: Processor P_4 loads x=3 from the same memory

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Cache Coherence (4/6)

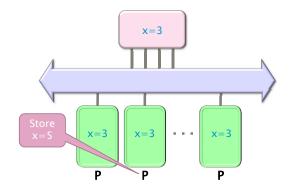


Figure: Processor P_2 issues a write x=5

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Cache Coherence (5/6)

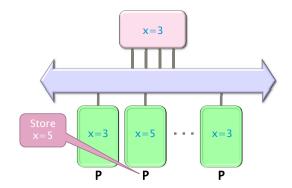


Figure: Processor P_2 writes x=5 in his local cache

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Cache Coherence (6/6)

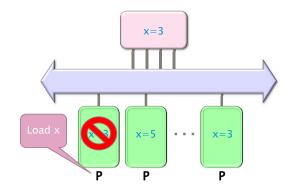


Figure: Processor P_1 issues a read x, which is now invalid in its cache

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MSI Protocol

- In this cache coherence protocol each block contained inside a cache can have one of three possible states:
 - M: the cache line has been modified and the corresponding data is inconsistent with the backing store; the cache has the responsibility to write the block to the backing store when it is evicted.
 - S: this block is unmodified and is **shared**, that is, exists in at least one cache. The cache can evict the data without writing it to the backing store.
 - I: this block is **invalid**, and must be fetched from memory or another cache if the block is to be stored in this cache.
- These coherency states are maintained through communication between the caches and the backing store.
- The caches have different responsibilities when blocks are read or written, or when they learn of other caches issuing reads or writes for a block.

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True Sharing and False Sharing

• True sharing:

- True sharing cache misses occur whenever two processors access the same data word
- True sharing requires the processors involved to explicitly synchronize with each other to ensure program correctness.
- A computation is said to have **temporal locality** if it re-uses much of the data it has been accessing.
- Programs with high temporal locality tend to have less true sharing.

• False sharing:

- False sharing results when different processors use different data that happen to be co-located on the same cache line
- A computation is said to have **spatial locality** if it uses multiple words in a cache line before the line is displaced from the cache
- Enhancing spatial locality often minimizes false sharing
- See Data and Computation Transformations for Multiprocessors by J.M. Anderson, S.P. Amarasinghe and M.S. Lam http://suif.stanford.edu/papers/anderson95/paper.html

Multi-core processor (cntd)

• Advantages:

- Cache coherency circuitry operate at higher rate than off-chip.
- Reduced power consumption for a dual core vs two coupled single-core processors (better quality communication signals, cache can be shared)

• Challenges:

- Adjustments to existing software (including OS) are required to maximize performance
- Production yields down (an Intel guad-core is in fact a double dual-core)
- Two processing cores sharing the same bus and memory bandwidth may limit performances
- High levels of false or true sharing and synchronization can easily overwhelm the advantage of parallelism

CS 3101 24 / 49

Plan

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2 Concurrency Platforms

- An overview of Cilk++
- Race Conditions and Cilkscreen
- MMM in Cilk++

From Cilk to Cilk++

- Cilk has been developed since 1994 at the MIT Laboratory for Computer Science by Prof. Charles E. Leiserson and his group, in particular by Matteo Frigo.
- Besides being used for research and teaching, Cilk was the system used to code the three world-class chess programs: Tech, Socrates, and Cilkchess.
- Over the years, the implementations of Cilk have run on computers ranging from networks of Linux laptops to an 1824-nodes Intel Paragon.
- From 2007 to 2009 Cilk has lead to Cilk++, developed by Cilk Arts, an MIT spin-off, which was acquired by Intel in July 2009 and became Cilk Plus, see http://www.cilk.com/
- Cilk++ can be freely downloaded at http://software.intel.com/en-us/articles/download-intel-ci
- Cilk is still developed at MIT http://supertech.csail.mit.edu/cilk/______

CS 3101 26 / 49

Cilk ++

- Cilk++ (resp. Cilk) is a small set of linguistic extensions to C++ (resp. C) supporting fork-join parallelism
- Both Cilk and Cilk++ feature a provably efficient work-stealing scheduler.
- Cilk++ provides a hyperobject library for parallelizing code with global variables and performing reduction for data aggregation.
- Cilk++ includes the Cilkscreen race detector and the Cilkview performance analyzer.

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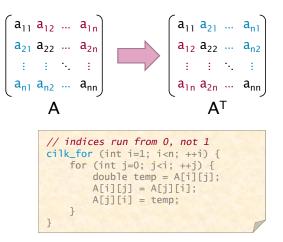
Nested Parallelism in Cilk ++

```
int fib(int n)
{
    if (n < 2) return n;
    int x, y;
    x = cilk_spawn fib(n-1);
    y = fib(n-2);
    cilk_sync;
    return x+y;
}</pre>
```

- The named child function cilk_spawn fib(n-1) may execute in parallel with its parent executes fib(n-2).
- Cilk++ keywords cilk_spawn and cilk_sync grant permissions for parallel execution. They do not command parallel execution.

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Loop Parallelism in Cilk ++



The iterations of a cilk_for loop may execute in parallel.

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Introduction to Multicore Programming

CS 3101 29 / 49

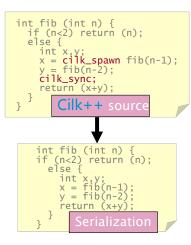
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Serial Semantics (1/2)

- Cilk (resp. Cilk++) is a multithreaded language for parallel programming that generalizes the semantics of C (resp. C++) by introducing linguistic constructs for parallel control.
- Cilk (resp. Cilk++) is a faithful extension of C (resp. C++):
 - The C (resp. C++) elision of a Cilk (resp. Cilk++) is a correct implementation of the semantics of the program.
 - Moreover, on one processor, a parallel Cilk (resp. Cilk++) program scales down to run nearly as fast as its C (resp. C++) elision.
- To obtain the serialization of a Cilk++ program

```
#define cilk_for for
#define cilk_spawn
#define cilk_sync
```

Serial Semantics (2/2)



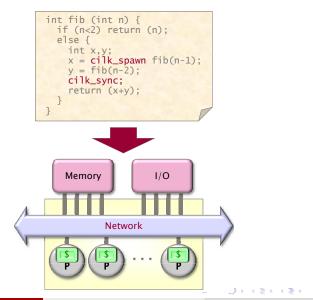
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An overview of Cilk++

Scheduling (1/3)



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 CS 3101 32 / 49

Scheduling (2/3)

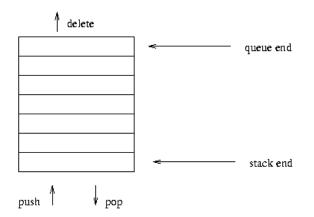
- Cilk/Cilk++ randomized work-stealing scheduler load-balances the computation at run-time. Each processor maintains a ready deque:
 - A ready deque is a double ended queue, where each entry is a procedure instance that is ready to execute.
 - Adding a procedure instance to the bottom of the deque represents a procedure call being spawned.
 - A procedure instance being deleted from the bottom of the deque represents the processor beginning/resuming execution on that procedure.
 - Deletion from the top of the deque corresponds to that procedure instance being stolen.
- A mathematical proof guarantees near-perfect linear speed-up on applications with sufficient parallelism, as long as the architecture has sufficient memory bandwidth.
- A spawn/return in Cilk is over 100 times faster than a Pthread create/exit and less than 3 times slower than an ordinary C function call on a modern Intel processor.

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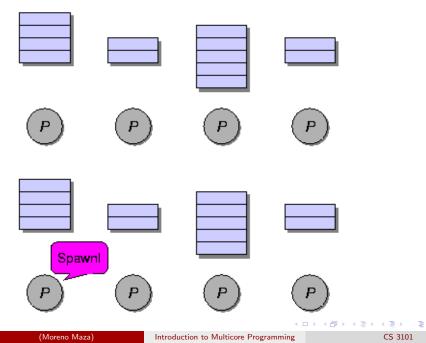
Introduction to Multicore Programming

CS 3101 33 / 49

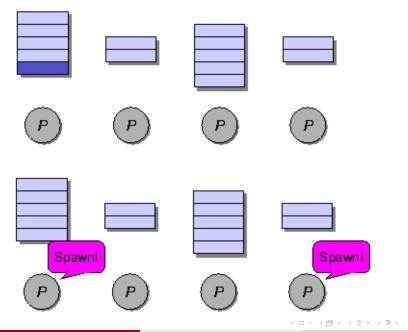
Scheduling (2/3)



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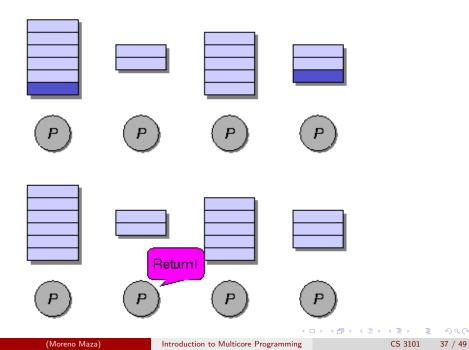
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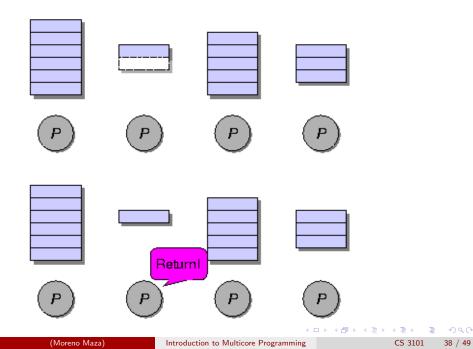
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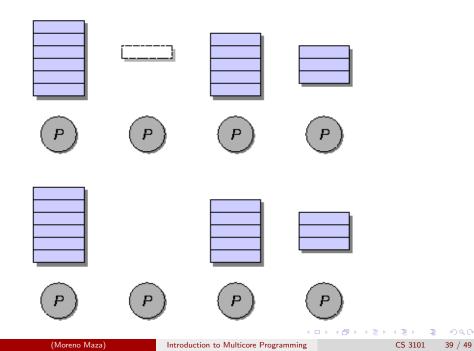
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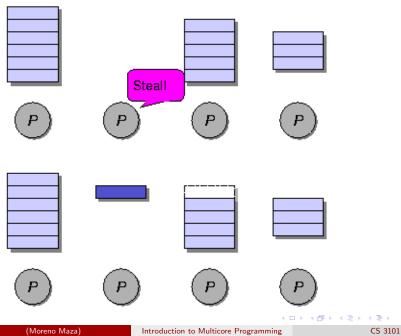


Concurrency Platforms An overview of Cilk++

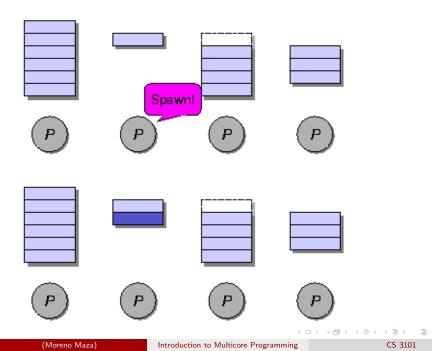


Concurrency Platforms An overview of Cilk++



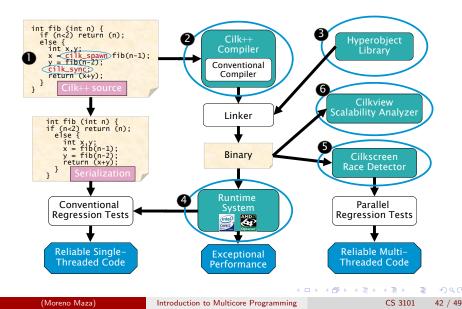


2 40 / 49 Concurrency Platforms An overview of Cilk++

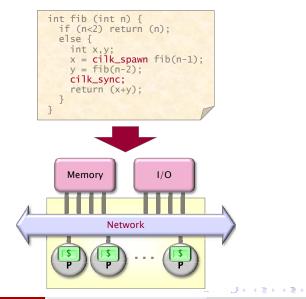


41 / 49

The Cilk++ Platform



Scheduling



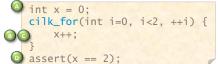
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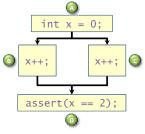
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Race Bugs (1/3)



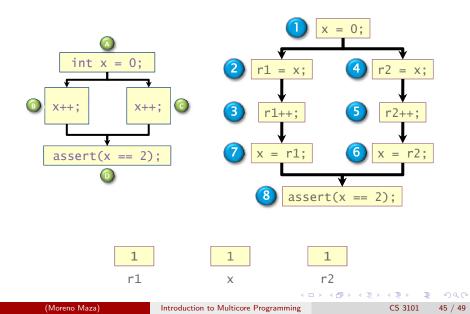




Dependency Graph

- Iterations of a cilk_for should be independent.
- Between a cilk_spawn and the corresponding cilk_sync, the code of the spawned child should be independent of the code of the parent, including code executed by additional spawned or called children.
- The arguments to a spawned function are evaluated in the parent before the spawn occurs.

Race Bugs (2/3)



Race Bugs (3/3)

- Watch out for races in packed data structures such as: struct{ char a; char b; } Updating x.a and x.b in parallel can cause races.
- If an ostensibly deterministic Cilk++ program run on a given input could possibly behave any differently than its serialization, Cilkscreen race detector guarantees to report and localize the offending race.
- Employs a regression-test methodology (where the programmer provides test inputs) and dynamic instrumentation of binary code.
- Identifies files-names, lines and variables involved in the race.
- Runs about 20 times slower than real-time.

```
template<typename T> void multiply_iter_par(int ii, int jj, int kk,
        T* C)
{
        cilk_for(int i = 0; i < ii; ++i)
        for (int k = 0; k < kk; ++k)
            cilk_for(int j = 0; j < jj; ++j)
                  C[i * jj + j] += A[i * kk + k] + B[k * jj + j];
}
```

Does not scale up well due to a poor locality and uncontrolled granularity.

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```
template<typename T> void multiply_rec_seq_helper(int i0, int i1, int j0,
    int j1, int k0, int k1, T* A, ptrdiff_t lda, T* B, ptrdiff_t ldb, T* C,
   ptrdiff_t ldc)
ſ
    int di = i1 - i0;
    int dj = j1 - j0;
    int dk = k1 - k0:
    if (di >= dj && di >= dk && di >= RECURSION_THRESHOLD) {
        int mi = i0 + di / 2:
        multiply_rec_seq_helper(i0, mi, j0, j1, k0, k1, A, lda, B, ldb, C, ldc);
        multiply_rec_seq_helper(mi, i1, j0, j1, k0, k1, A, lda, B, ldb, C, ldc);
   } else if (dj >= dk && dj >= RECURSION_THRESHOLD) {
        int mj = j0 + dj / 2;
       multiply_rec_seq_helper(i0, i1, j0, mj, k0, k1, A, lda, B, ldb, C, ldc);
        multiply_rec_seq_helper(i0, i1, mj, j1, k0, k1, A, lda, B, ldb, C, ldc);
   } else if (dk >= RECURSION_THRESHOLD) {
        int mk = k0 + dk / 2;
        multiply_rec_seq_helper(i0, i1, j0, j1, k0, mk, A, lda, B, ldb, C, ldc);
        multiply_rec_seq_helper(i0, i1, j0, j1, mk, k1, A, lda, B, ldb, C, ldc);
   } else {
        for (int i = i0; i < i1; ++i)
            for (int k = k0; k < k1; ++k)
                for (int j = j0; j < j1; ++j)
                    C[i * 1dc + j] += A[i * 1da + k] * B[k * 1db + j];
   }
3
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```

CS 3101 48 / 49

```
template<typename T> inline void multiply_rec_seq(int ii, int jj, i:
    T* B, T* C)
{
    multiply_rec_seq_helper(0, ii, 0, jj, 0, kk, A, kk, B, jj, C, j)
}
```

Multiplying a 4000x8000 matrix by a 8000x4000 matrix

- on 32 cores = 8 sockets x 4 cores (Quad Core AMD Opteron 8354) per socket.
- The 32 cores share a L3 32-way set-associative cache of 2 Mbytes.

#core	Elision (s)	Parallel (s)	speedup
8	420.906	51.365	8.19
16	432.419	25.845	16.73
24	413.681	17.361	23.83
32	389.300	13.051	29.83