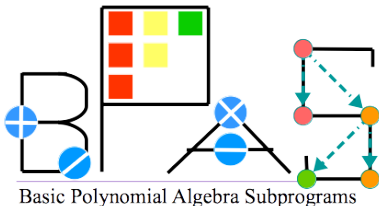


Employing C++ Templates in the Design of a Computer Algebra Library



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The BPAS Library

Basic Polynomial Algebra Subprograms (BPAS) [2] provides **high-performance polynomial algebra**.

- High performance: core implementation in C considers data locality, cache complexity, and parallelism for modern multi-core architectures
- Easy to use: **“Dynamic” Object-Oriented interface** in C++ is a light-weight wrapper of the underlying, optimized C code.

Notable highly-optimized operations include:

- FFTs, parallel integer polynomial multiplication, modular polynomial arithmetic, parallel Taylor shift, real root isolation (ICMS 2014 [5])
- Big prime field FFTs, arithmetic in $\mathbb{Z}/p\mathbb{Z}$ for large characteristic [6]
- Sparse polynomial arithmetic, pseudo-division, normal form [4]
- Polynomial system solving: parallel triangular decomposition via regular chains [3]

Outline

- 1 Motivation in Design
- 2 Background
- 3 Algebraic Hierarchy as a Templated Class Hierarchy
- 4 Polynomials in a Templated Class Hierarchy

Motivation: Usability

BPAS is concerned with **accessibility**, **interoperability**, and **usability**.

→ Open-source and written in C/C++ provides the former two.

To achieve usability, we consider best practices for its interface.

1 Natural: a symmetric encoding of the algebraic hierarchy

field \subset Euclidean domain \subset GCD domain \subset integral domain \subset ring

2 Easy to use: an object-oriented design with well-defined interfaces.
A so-called **algebraic class hierarchy**: rings are classes and elements of a ring are objects

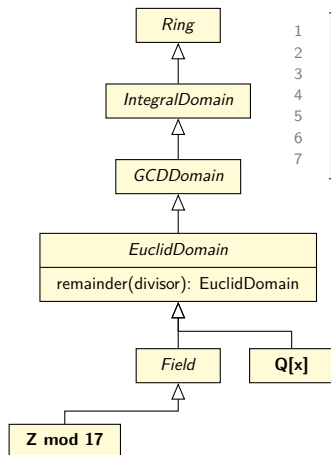
3 Encapsulation: hide complexity of low-level code; class interfaces

4 Extensible: adaptable to new (user-created) types, type composition

5 Type safe: compile-time type safety and mathematical type safety

Motivation: Type Safety

A naive implementation of the algebraic hierarchy as a class hierarchy creates mathematically unsafe operations via polymorphism.



```
1 class EuclidDomain {  
2     EuclidDomain remainder(EuclidDomain& divisor);  
3 }  
4  
5 Zmod17 a;  
6 RationalPoly b;  
7 EuclidDomain r = a.remainder(b);
```

- $\mathbb{Z}/17\mathbb{Z}$ and $\mathbb{Q}[x]$ are Euclidean domains
- the code is valid via polymorphism
- could compile, but then issues at runtime.

Existing Solutions

In other compiled libraries, mathematical type safety is only a runtime property maintained through runtime value checks.

- In Singular's libpolys [7], all algebraic types are a single class. Instance variables (Booleans, enums) store properties of rings
- In CoCoA [1] rings and elements of a ring are separate classes. Elements hold references to their “owning” ring which are compared at runtime and errors thrown if not identical.
- In LinBox [8] rings and elements are again distinct, with references to abstract ring elements being downcasted for operations.

Our Goal: provide both compile-time mathematical type safety and a natural, extensible object-oriented hierarchy for the algebraic hierarchy

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Templates in C++

A **class template** in C++ is a parameterized class definition

- *template instantiation*: providing a particular value for a template parameter
- **compile-time** code generation and *overload resolution* occurs
- synonymous definitions for function templates

Template metaprogramming uses templates to control and modify a program's code or compilation

- facilitates compile-time code generation
- facilitates **compile-time code evaluation**

Compile-Time Introspection

Templates allow for *compile-time introspection*

→ compile-time evaluation of code to determine properties of a type

```
1  struct Foo {
2      typedef int X;
3  };
4
5  template<typename T> char test(typename T::X const*);
6
7  template<typename T> int test(...);
8
9  #define type_has_X(T) (sizeof(test<T>(NULL)) == 1);
10
11 std::cout << "Foo has X: " << type_has_X(Foo);
12 std::cout << "int has X: " << type_has_X(int);
```

→ if T has type X, then compile-time overload resolution chooses first definition with return type char (size == 1)

→ else, second definition is chosen with return type int (size >= 2)

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Algebraic Class Hierarchy

The algebraic hierarchy as a class hierarchy with mathematical type safety

Solution: an **abstract class template hierarchy**.

- abstract classes: well-defined interfaces, default behaviour
- inheritance incrementally extends/builds interface
- template parameter modifies interface to restrict method parameters

```
1  template <class Derived>
2  class Ring {...};
3
4  template <class Derived>
5  class IntegralDomain : Ring<Derived> {...};
6
7  template <class Derived>
8  class GCDDomain : IntegralDomain<Derived> {...};
9
10 template <class Derived>
11 class EuclidDomain : GCDDomain<Derived> {
12     Derived remainder(Derived& divisor);
13 }
```

Algebraic Class Hierarchy: Static Polymorphism

Static polymorphism via *Curiously Recurring Template Pattern*: concrete class is used as template parameter of super class.

- function resolution occurs at compile-time
- method declaration restricts params to be compile-time compatible

```
1  template <class Derived>
2  class EuclidDomain : GCDDomain<Derived> {
3      Derived remainder(const Derived& divisor);
4  };
5
6  class Integer : EuclidDomain<Integer> {...}; //CRTP
7  //Integer remainder(const Integer& divisor);
8
9  class RationalPoly : EuclidDomain<RationalPoly> {...}; //CRTP
10 //RationalPoly remainder(const RationalPoly& divisor);
11
12 Integer x; RationalPoly p;
13
14 //compiler error: EuclidDomain<RationalPoly>::remainder
15 //                takes RationalPoly as parameter
16 RationalPoly r = p.remainder(x);
```

Algebraic Class Hierarchy: Adding Flexibility

Disjoint class hierarchies is too restrictive. Allow *implicit conversion* by defining constructors, e.g. for natural ring embeddings $\mathbb{Z} \hookrightarrow \mathbb{Q} \hookrightarrow \mathbb{Q}[x]$

```
1  class Integer : EuclidDomain<Integer> {};  
2  
3  class RationalPoly : EuclidDomain<RationalPoly> {  
4      RationalPoly(Integer x) {...};  
5  };  
6  
7  Integer x;  
8  RationalPoly p;  
9  
10 //no error: implicit conversion, Integer to RationalPoly  
11 RationalPoly r = p.reminder(x);
```

- Explicitly defining constructors gives permission for compatibility between types at compile-time
- *cf.* working in a restrictive manner: allow everything at compile-time and catch incompatibility at runtime

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Algebraic Class Hierarchy with Polynomials

Extend abstract class template hierarchy to include polynomials

→ parameterize polynomial abstract classes by coefficient ring

```
1  template <class Derived>
2  class Ring {...};
3
4  template <class CoefRing, class Derived>
5  class Poly : Ring<Derived> {...};
6
7  class RationalPoly : Poly<RationalNumber, RationalPoly> {...};
```

Problem: What if CoefRing is not actually a ring?

→ e.g. `Poly<std::string>` or `Poly::<Apple>`

Problem: polynomial rings form different algebraic types depending on the ground ring

→ e.g. $\mathbb{Q}[x]$ is a Euclidean domain, $\mathbb{Z}[x]$ is an integral domain

Constraining the Ground Ring

At compile-time ensure that a polynomial's coefficient ring is an actual ring with template metaprogramming.

`Derived_from<T, Base>`: statically determines if `T` is a subclass of `Base`, creating a compiler-error if not

- inheriting from `Derived_from` forces evaluation at compile-time during template instantiation
- Coefficient ring must be a subclass of `Ring`
- `Poly` can assume `CoefRing` has a certain interface at minimum

```
1  template <class T, class Base>
2  class Derived_from {...};
3
4  template <class CoefRing, class Derived>
5  class Poly : Ring<Derived>,
6             Derived_from<CoefRing, Ring<CoefRing>> {...};
```


Adapting to Different Coefficient Rings (1/2)

Determine type of coefficient ring using *compile-time introspection*

- **Conditional inheritance** then determines correct algebraic type and interface for polynomials over that ring
- “Dynamic” type creation via introspection, template instantiation

`is_base_of<T, Base>::value`

- compile-time Boolean value determines if T is a subclass of Base

`conditional<Bool, T1, T2>::value`

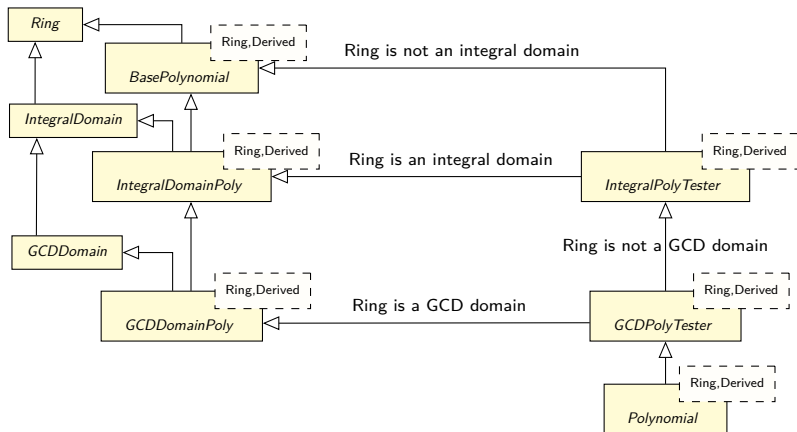
- A compile-time tertiary conditional operator for choosing types
- `Bool ? T1 : T2`

```
1 template <class CRing, class Derived>
2 class Poly : conditional< is_base_of<CRing, Field<CRing>>::value,
3                          EuclidDomain<Derived>,
4                          Ring<Derived>
5                          >::value {...};
```

Adapting to Different Coefficient Rings (2/2)

A chain of conditional's create a case-discussion at compile-time

- *Tester* hierarchy separates introspection from actual interface
- Concrete classes inherit from *Polynomial* to automatically determine their type and interface



Conclusions and Future Work

Algebraic Class Hierarchy as an abstract class template hierarchy

- Direct object-oriented encoding of algebraic types for strict interfaces
- Compile-time type safety, implicit conversion allows compatibility
- Properties of rings (classes) can be exploited with introspection
- Adaptive polynomial class hierarchy through conditional inheritance
 - ↳ More generally, conditionally exposes/adds methods to an interface

In future:

- The hierarchy will be extended to include power series, polynomials over prime fields
- A Python interface will be added on top of the C++ interface

Thank You!

I look forward to your questions:

- during the live Q/A session, or
- via email, Alex Brandt <abrandt5@uwo.ca>

References

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