# CS4403 - CS9535: An Overview of Parallel Computing

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#### Plan



## 2 Types of Parallelism

### 3 Concurrency Platforms: Three Examples

- Julia
- Cilk
- CUDA
- MPI

#### Plan



#### Types of Parallelism

#### B) Concurrency Platforms: Three Examples

- Julia
- Cilk
- CUDA
- MPI

#### The Pentium Family



#### Hardware

#### **Multicore processors**



#### **Multicore processors**



Main Memory

# The CPU-Memory Gap

# The increasing gap between DRAM, disk, and CPU speeds.



Once uopn a time, every thing was slow in a computer ....

## Graphics processing units (GPUs)



#### **Distributed Memory**



- Distributed memory systems require a communication network to connect inter-processor memory.
- Processors have their own local memory and operate independently.
- Memory addresses in one processor do not map to another processor, so there is no concept of global address space across all processors.
- Data exchange between processors is managed by the programmer , not by the hardware.

#### Hybrid Distributed-Shared Memory



- The largest and fastest computers in the world today employ both shared and distributed memory architectures.
- Current trends seem to indicate that this type of memory architecture will continue to prevail.
- While this model allows for applications to scale, it increases the complexity of writing computer programs.

#### Plan



## 2 Types of Parallelism

Concurrency Platforms: Three Examples

- Julia
- Cilk
- CUDA
- MPI

#### Pipelining



- Pipelining is a common way to organize work with the objective of optimizing throughput.
- It turns out that this is also a way to execute concurrently several tasks (that is, work units) processable by the same pipeline.

#### Instruction pipeline



- Above is a generic pipeline with four stages: Fetch, Decode, Execute, Write-back.
- The top gray box is the list of instructions waiting to be executed; the bottom gray box is the list of instructions that have been completed; and the middle white box is the pipeline.

#### Data parallelism



- The data set is typically organized into a common structure, such as an array.
- A set of tasks work collectively on that structure, however, each task works on a different region.
- Tasks perform the same operation on their region of work, for example, "multiply every array element by some value".

```
Task parallelism (1/4)
```

```
program:
...
if CPU="a" then
    do task "A"
else if CPU="b" then
    do task "B"
end if
...
end program
```

- Task parallelism is achieved when each processor executes a different thread (or process) on the same or different data.
- The threads may execute the same or different code.

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#### Task parallelism (2/4)

Code executed by CPU "a":

```
program:
...
do task "A"
...
end program
```

Code executed by CPU "b":

program: ... do task "B" ... end program

- In the general case, different execution threads communicate with one another as they work.
- Communication usually takes place by passing data from one thread to the next as part of a work-flow.

#### **Stencil computations**



- In scientific computing, stencil computations are very common.
- Typically, a procedure updates array elements according to some fixed pattern, called stencil.
- In the above, a 2D array of  $100 \times 100$  elements is updated by the stencil T.

#### Pascal triangle construction: another stencil computation



Construction of the Pascal Triangle: nearly the simplest stencil computation!

#### Plan





**3** Concurrency Platforms: Three Examples

- Julia
- Cilk
- CUDA
- MPI

#### Distributed arrays and parallel reduction (1/4)

```
[moreno@compute-0-3 ~]$ julia -p 5
```

```
_ _ _(_)_ | A fresh approach to technical computing
(_) | (_) (_) | Documentation: http://docs.julialang.org
_ _ _ | |_ ___ | Type "help()" to list help topics
| | | | | | | /_ (` | |
| | | | | | (_| | | Version 0.2.0-prerelease+3622
_/ |\__'_|_||\__'| | Commit c9bb96c 2013-09-04 15:34:41 UTC
|__/ | x86_64-redhat-linux
```

```
julia> da = @parallel [2i for i = 1:10]
10-element DArray{Int64,1,Array{Int64,1}}:
    2
    4
    6
    8
    10
    12
    14
    16
    18
    20
```

#### Distributed arrays and parallel reduction (2/4)

```
julia> procs(da)
4-element Array{Int64,1}:
 3
 4
 5
julia> da.chunks
4-element Array{RemoteRef,1}:
RemoteRef(2,1,1)
RemoteRef(3,1,2)
RemoteRef(4,1,3)
RemoteRef(5,1,4)
julia>
julia> da.indexes
4-element Array{(Range1{Int64},),1}:
 (1:3.)
 (4:5,)
 (6:8.)
 (9:10,)
julia> da[3]
6
julia> da[3:5]
3-element SubArray{Int64,1,DArray{Int64,1,Array{Int64,1}},(Range1{Int64},)}:
 6
 8
 10
```

#### Julia

#### Distributed arrays and parallel reduction (3/4)

```
julia> fetch(@spawnat 2 da[3])
6
julia>
julia> { (@spawnat p sum(localpart(da))) for p=procs(da) }
4-element Array{Any,1}:
RemoteRef(2,1,71)
RemoteRef(3,1,72)
RemoteRef(4, 1, 73)
RemoteRef(5, 1, 74)
julia>
julia> map(fetch, { (@spawnat p sum(localpart(da))) for p=procs(da) })
4-element Array{Any,1}:
12
 18
42
38
julia>
julia> sum(da)
110
```

#### Distributed arrays and parallel reduction (4/4)

```
julia> reduce(+, map(fetch,
                 { (@spawnat p sum(localpart(da))) for p=procs(da) }))
110
julia>
julia> preduce(f,d) = reduce(f,
                           map(fetch,
                             { (@spawnat p f(localpart(d))) for p=procs(d) }))
# methods for generic function preduce
preduce(f,d) at none:1
julia> function Base.minimum(x::Int64, y::Int64)
       \min(x, y)
       end
minimum (generic function with 10 methods)
julia> preduce(minimum, da)
2
```

#### Task Parallelism in CilkPlus

```
int fib(int n)
{
    if (n < 2) return n;
    int x, y;
    x = cilk_spawn fib(n-1);
    y = fib(n-2);
    cilk_sync;
    return x+y;
}</pre>
```

- The named child function cilk\_spawn fib(n-1) may execute in parallel with its parent
- CilkPlus keywords cilk\_spawn and cilk\_sync grant permissions for parallel execution. They do not command parallel execution.

#### Scheduling



A **scheduler**'s job is to map a computation to particular processors. Such a mapping is called a **schedule**.

- If decisions are made at runtime, the scheduler is *online*, otherwise, it is *offline*
- CilkPlus's scheduler maps strands onto processors dynamically at runtime.

#### The CilkPlus Platform



#### Benchmarks for parallel divide-and-conquer matrix multiplication

Multiplying a 4000x8000 matrix by a 8000x4000 matrix

- on 32 cores = 8 sockets x 4 cores (Quad Core AMD Opteron 8354) per socket.
- The 32 cores share a L3 32-way set-associative cache of 2 Mbytes.

#core	Elision (s)	Parallel (s)	speedup
8	420.906	51.365	8.19
16	432.419	25.845	16.73
24	413.681	17.361	23.83
32	389.300	13.051	29.83

#### **Uisng** Cilkview



Speedup for 'multiply 5000x10000 matrix by 10000x5000 matrix'

#### **CUDA** design goals

- Enable heterogeneous systems (i.e., CPU+GPU)
- Scale to 100's of cores, 1000's of parallel threads
- $\bullet~$  Use C/C++ with minimal extensions
- Let programmers focus on parallel algorithms (as much as possible).



#### Example: increment array elements (1/2)

### Increment N-element vector a by scalar b



blockIdx.x=0 blockDim x=4threadIdx.x=0,1,2,3 idx=0,1,2,3

blockIdx.x=1 blockDim x=4threadIdx.x=0,1,2,3 idx=4,5,6,7

blockldx x=2blockIdx.x=3 blockDim x=4threadIdx.x=0,1,2,3 idx=8,9,10,11

blockDim.x=4threadIdx.x=0,1,2,3 idx=12.13.14.15

See our example number 4 in /usr/local/cs4402/examples/4

#### Example: increment array elements (2/2)

#### **CPU program**

#### **CUDA** program

```
global void increment gpu(float *a, float b, int N)
void increment_cpu(float *a, float b, int N)
                                              {
{
                                                  int idx = blockldx.x * blockDim.x + threadldx.x;
    for (int idx = 0; idx<N; idx++)
         a[idx] = a[idx] + b;
                                                  if (idx < N)
                                                       a[idx] = a[idx] + b;
}
                                              }
                                             void main()
void main()
Ł
                                                ....
  ....
                                                  dim3 dimBlock (blocksize);
    increment cpu(a, b, N);
                                                  dim3 dimGrid( ceil( N / (float)blocksize) );
}
                                                  increment gpu<<<dimGrid, dimBlock>>>(a, b, N);
                                              }
```

#### CUDA

## A Common programming strategy

#### Partition data into subsets that fit into shared memory



#### A Common Programming Strategy

Handle each data subset with one thread block



#### A Common programming strategy

Load the subset from global memory to shared memory, using multiple threads to exploit memory-level parallelism.



#### A Common programming strategy

Perform the computation on the subset from shared memory.



#### A Common programming strategy

Copy the result from shared memory back to global memory.



#### Example

Here's a common example:

- Have the master (rank 0) process create some strings and send them to the worker processes
- The worker processes modify the string and send it back to the master

#### Example Code (1)

```
/*
 "Hello World" MPI Test Program
*/
#include <mpi.h>
#include <stdio.h>
#include <string.h>
#define BUFSIZE 128
#define TAG 0
int main(int argc, char *argv[])
  char idstr[32];
  char buff[BUFSIZE];
   int numprocs;
   int myid;
  int i:
  MPI_Status stat;
```

#### Example Code (2)

```
/* all MPI programs start with MPI_Init; all 'N'
 * processes exist thereafter
*/
MPI_Init(&argc.&argv);
/* find out how big the SPMD world is */
MPI_Comm_size (MPI_COMM_WORLD, & num procs);
/* and this processes ' rank is */
MPI_Comm_rank (MPI_COMM_WORLD, & myid);
/* At this point, all programs are running equivalently,
 * the rank distinguishes the roles of the programs in
 * the SPMD model, with rank 0 often used specially...
 */
```

#### Example Code (3)

```
if(myid == 0)
  printf("%d: We have %d processors\n", myid, numprocs);
  for (i = 1; i < num procs ; i++)
    sprintf(buff, "Hello %d! ", i);
    MPI_Send(buff, BUFSIZE, MPI_CHAR, i, TAG,
             MPL_COMM_WORLD);
  for ( i =1; i < numprocs ; i++)
    MPI_Recv(buff, BUFSIZE, MPI_CHAR, i, TAG,
             MPI_COMM_WORLD, &stat);
    printf("%d: %s\n", myid, buff);
```

#### Example Code (4)

```
else
 /* receive from rank 0: */
 MPI_Recv(buff, BUFSIZE, MPI_CHAR, 0, TAG,
           MPL_COMM_WORLD, & stat);
  sprintf(idstr, "Processor %d ", myid);
  strncat(buff, idstr, BUFSIZE-1);
  strncat(buff, "reporting for duty", BUFSIZE-1);
 /* send to rank 0: */
 MPI_Send(buff, BUFSIZE, MPI_CHAR, 0, TAG,
           MPLCOMM_WORLD);
/* MPI Programs end with MPI Finalize; this is a weak
 * synchronization point
 */
MPI_Finalize():
return 0;
```