

On solving parametric polynomial systems

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joint work with

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1 Motivation and background

2 Main results

3 Conclusion and future work

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Related work

- 1 ...
- 2 Comprehensive Gröbner bases (Weispfenning, 1992)
- 3 Comprehensive Gröbner systems (Montes, 2004) (Kapur, Yao Sun, Wang 2010-2011)
- 4 Border polynomial (Yang, Xia and Hou, 1999)
- 5 Discriminant variety (Lazard and Rouillier, 2007)
- 6 Comprehensive triangular decomposition (Chen, Golubitsky, Lemaire, MMM, Pan 2007)
- 7 ...

Solving a parametric polynomial system?

Input: $f := ax^2 + x + 1$ with parameter a and $(a, x) \in \mathbb{R}^2$

Output:

$$\begin{cases} x = \frac{-1+\sqrt{1-4a}}{2a} \text{ or } x = \frac{-1-\sqrt{1-4a}}{2a}, & \text{when } a \neq 0 \\ x = -1, & \text{when } a = 0 \end{cases}$$

“Generically”, the properties of solutions depend on the parameter values continuously

- **Generically:** the points related to “discontinuity” are few
- **Properties of the solutions:** number, value, representation form (regular chains, Gröbner bases)

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Various notions of continuity

Let $f := ax^2 + x + 1$ with parameter a and α be a fix parameter value.

Example (Simple solutions)

Let $\alpha \notin \{0, \frac{1}{4}\}$. For all a near α , f has 2 complex **simple** roots.

Example (Real solutions)

Let $\alpha \in (0, \frac{1}{4})$. For all a near α , f has 2 **simple real** roots α_1, α_2 , which are semi-algebraic functions of a :

$$\alpha_1 = \frac{-1 + \sqrt{1 - 4a}}{2a}, \alpha_2 = \frac{-1 - \sqrt{1 - 4a}}{2a}$$

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More examples

Let $f_2 := ay^2 + xy - 1$, $f_1 := (a - 1)x^2 - 1$ and $S := \{f_1 = 0, f_2 = 0\}$ with parameter a

Example (Gröbner bases)

Let $\alpha \notin \{0, 1\}$. For all $a = \beta$ near α , the reduced Gröbner basis of the polynomial ideal $\langle f_1, f_2 \rangle|_{a=\beta}$ w.r.t. $x \prec y$ has the formula:

$$\left\{ \frac{f_2}{a}, \frac{f_1}{a-1} \right\}_{a=\beta}.$$

Example (Triangular decomposition)

Let $\alpha \notin \{0, 1\}$. For all $a = \beta$ near α ,

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forms a triangular decomposition of $S|_{a=\beta}$.

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Notations

Parameters/values: $U = u_1, u_2, \dots, u_d / \mathbb{C}^d$

Unknowns/values: $X = x_1, x_2, \dots, x_s / \mathbb{C}^s$

Parametric algebraic system $S := [F, H]$:

$$\begin{cases} f_1 = f_2 = \dots = f_\ell = 0 \\ h_1 \neq 0, h_2 \neq 0, \dots, h_k \neq 0 \end{cases}$$

where

$$F = \{f_1, f_2, \dots, f_\ell\},$$

$$H = \{h_1, h_2, \dots, h_k\},$$

$$F, H \subset \mathbb{Q}[U, X].$$

$Z(S)$: zero set of S in \mathbb{C}^{d+s}

Assumption: S is *well-determinate*, i.e.

$$\mathcal{I} := \langle F \rangle : \left(\prod_{h \in H} h \right)^\infty$$

is of dimension d and U is maximally algebraically independent, modulo \mathcal{I} .

Two notions of continuity

$$\begin{aligned}\Pi_U : Z(S) \subset \mathbb{C}^{s+d} &\mapsto \mathbb{C}^d \\ \Pi_U(x_1, \dots, x_s, u_1, \dots, u_d) &= (u_1, \dots, u_d)\end{aligned}$$

Definition

Let α in \mathbb{C}^d . We say that S is

- 1 Z -continuous at α : if there exists an open ball \mathcal{O}_α centered at α s.t. for any $\beta \in \mathcal{O}_\alpha$ we have $\#(Z(S(\beta))) = \#(Z(S(\alpha)))$.
- 2 Π_U -continuous at α : if there exists an open ball \mathcal{O}_α centered at α and a finite partition, say $\{C_1, \dots, C_k\}$ of $\Pi_U^{-1}(\mathcal{O}_\alpha) \cap Z(S)$ such that for each $j \in \{1, \dots, k\}$

$$\Pi_U|_{C_j} : C_j \xrightarrow{\Pi_U} \mathcal{O}_\alpha$$

is a diffeomorphism.

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is a **diffeomorphism**.

Border polynomial and discriminant variety

We reformulate these two well-known concepts using the previous [continuity](#) notions.

Definition (Border polynomial)

A non-zero polynomial b in $\mathbb{Q}[U]$ is called a *border polynomial* (BP) of the parametric polynomial system S if the zero set $V(b)$ of b in \mathbb{C}^d contains all the points at which S is not Z -continuous.

Definition (Discriminant variety)

An algebraic set $\mathcal{W} \subsetneq \mathbb{C}^d$ is a *discriminant variety* of the parametric polynomial system S if \mathcal{W} contains all the points at which S is not Π_U -continuous.

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Remarks

- ① Π_U -continuity implies Z -continuity
- ② The minimal DV: the intersection of all DV
- ③ The “minimal” BP?: does not exist in general; see the case the minimal DV is not a hypersurface.

Motivation and contributions

- Are those different notions of continuity (and discontinuity) computatable?
- How are they related to each other?

Our contributions:

- Z -continuity and Π_U -continuity are equivalent for “triangular” systems
- An explicit form of BP/minimal DV for “triangular” systems
- A new characterization for the non-properness locus of the minimal DV of $\text{sat}(T)$
- The difference between the minimal DV of T and that of $\text{sat}(T)$
- Given T , characterize T' among all T' satisfying $\text{sat}(T') = \text{sat}(T)$ such that T' possessing the minimal BP.

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Equivalence BP-DV for triangular systems (1/2)

Let $S := [T, H]$ be a squarefree triangular algebraic system (STAS). Denote by $B_{sep}(T)$, $B_{ini}(T)$, $B_{ie}([T, H])$ respectively the set of the **irreducible factors** of

$$\prod_{t \in T} \text{ires}(\text{discrim}(t, \text{mvar}(t)), T), \prod_{t \in T} \text{ires}(\text{init}(t), T), \text{ and } \prod_{f \in H} \text{ires}(f, T).$$

Denote $\mathbf{BPS}(T) := B_{sep}(T) \cup B_{ini}(T) \cup B_{ie}([T, H])$.

Equivalence BP-DV for triangular systems (2/2)

Lemma

Let $b = \prod_{f \in B_{\text{sep}}(T) \cup B_{\text{ini}}(T) \cup B_{\text{ie}}([T, H])} f$; let $N := \prod_{f \in T} \text{mdeg}(f)$. Then for each parameter value $\alpha \in \mathbb{C}^d$:

- 1 if $b(\alpha) \neq 0$, then $\# Z(S(\alpha)) = N$ holds;
- 2 if $b(\alpha) = 0$, then $\# Z(S(\alpha))$ is either infinite or less than N .

(This means b is a border polynomial of S)

Proposition

The minimal discriminant variety of $S := [T, H]$ is

$$V\left(\prod_{f \in B_{\text{ini}}(T) \cup B_{\text{sep}}(T) \cup B_{\text{ie}}([T, H])} f\right).$$

clearly BP \equiv DV for STASes

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\mathcal{O}_∞ : set of non-properness of Π_U

$\mathcal{O}_\infty(S)$: the set of points where Π_U is not proper
($\mathcal{O}_\infty(S)$ is related to the number of solutions counting multiplicities)

Proposition

We have $\mathcal{O}_\infty(T) = V(\prod_{f \in B_{ini}(T)} f)$.

Proposition

For each $i = 1, \dots, s$, let g_i be a polynomial generating the principal ideal $\text{sat}(T) \cap \mathbb{Q}[U, x_i]$. Then we have

$$\mathcal{O}_\infty(\text{sat}(T)) = \cup_{i=1}^s V(\text{init}(g_i)).$$

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Discriminant variety: T vs $\text{sat}(T)$

Proposition

We have

$$DV_T \setminus DV_{\text{sat}(T)} \subseteq \mathcal{O}_\infty(T) \setminus \mathcal{O}_\infty(\text{sat}(T)).$$

Proposition

Let T_1 and T_2 be two regular chains satisfying $\text{sat}(T_1) = \text{sat}(T_2)$. If $B_{\text{ini}}(T_1) \subseteq B_{\text{ini}}(T_2)$ holds, then $B_{\text{ini}}(T_1) \cup B_{\text{sep}}(T_1) \subseteq B_{\text{ini}}(T_2) \cup B_{\text{sep}}(T_2)$ holds.

Theorem

Let T^* be another regular chain satisfying $\text{sat}(T) = \text{sat}(T^*)$. If T^* is *canonical*, then we have $B_{\text{ini}}(T^*) \subseteq B_{\text{ini}}(T)$.

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Summary and future work

Propose the framework of “continuity” to unify the notions of BP and DV

For an STAS $S := [T, H]$

- $b := \prod_{f \in B_{sep}(T) \cup B_{ini}(T) \cup B_{ie}([T, H])} f$ is a border polynomial of S
- $V(b = 0)$ is the minimal DV of S
- New characterization of \mathcal{O}_∞ :

$$\begin{aligned}\mathcal{O}_\infty(T) &= \prod_{f \in B_{ini}(T)} f = 0, \\ \mathcal{O}_\infty(\text{sat}(T)) &= \prod_{i \in \{1, 2, \dots, s\}} g_i = 0\end{aligned}$$

- $$DV_T \setminus DV_{\text{sat}(T)} \subseteq \mathcal{O}_\infty(T) \setminus \mathcal{O}_\infty(\text{sat}(T)).$$
- The regular chains in canonical form possess the smallest BPes.

Summary and future work

Future work:

- Show that Z -continuity and Π_U -continuity are equivalent for equidimensional systems
- Investigate the relation of other notions: comprehensive GB, comprehensive TD and the notion of BP or DV
- Design better algorithm to compute BP